

Reducing the Memory Gap between Hierarchical Lowrank Formats

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MAX PLANCK INSTITUTE
FOR MATHEMATICS IN THE SCIENCES



HIERARCHICAL MATRICES

Hierarchical Matrices

Approximate dense data $M_{\tau,\sigma} \in \mathbb{C}^{\#\tau \times \#\sigma}$ of $M \in \mathbb{C}^{n \times n}$ by

$$U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$$

with $U_{\tau,\sigma} \in \mathbb{C}^{\#\tau \times k}$, $V_{\tau,\sigma} \in \mathbb{C}^{\#\sigma \times k}$ and

$$k \ll \min(\#\tau, \#\sigma)$$

such that

$$\|M_{\tau,\sigma} - U_{\tau,\sigma} V_{\tau,\sigma}^H\| \leq \delta \quad \text{or}$$

$$\|M_{\tau,\sigma} - U_{\tau,\sigma} V_{\tau,\sigma}^H\| \leq \varepsilon \|M_{\tau,\sigma}\|$$

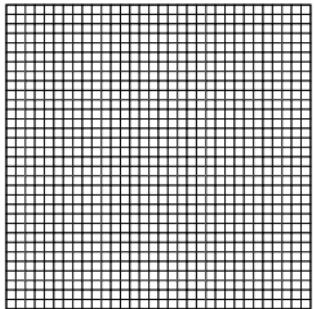
yielding an approximation \tilde{M} of M with $\mathcal{O}(n \log^\alpha n)$ storage.

In the literature, many different formats of (hierarchical) lowrank matrices exist.

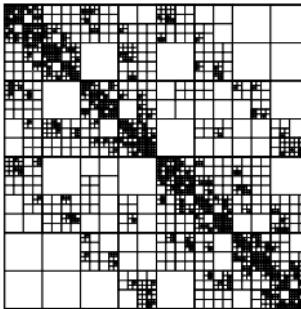
Hierarchical Matrices

Block structure

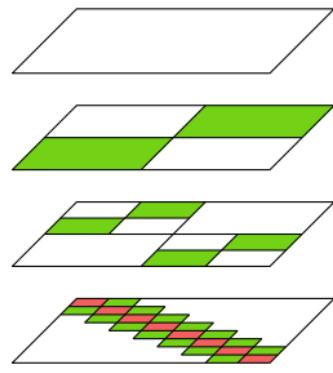
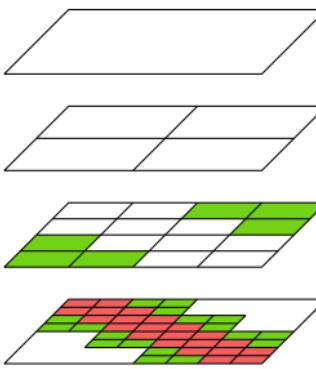
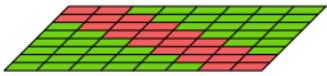
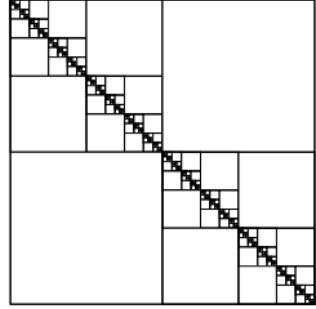
BLR/BLR²



$\mathcal{H}/\mathcal{H}^2$

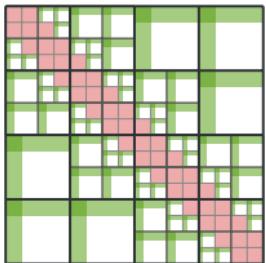


HODLR/HSS



Basis Representation

Separate Bases



$$M_{\tau,\sigma} = U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$$

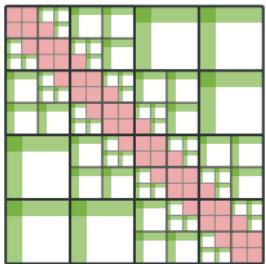
with

$$U_{\tau,\sigma} \in \mathbb{R}^{\#\tau \times k}, V_{\tau,\sigma} \in \mathbb{R}^{\#\sigma \times k}$$

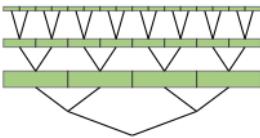
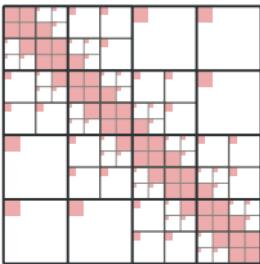
$$\mathcal{O}(n \log n)$$

Basis Representation

Separate Bases



Shared Bases



$$M_{\tau,\sigma} = U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$$

with

$$U_{\tau,\sigma} \in \mathbb{R}^{\#\tau \times k}, V_{\tau,\sigma} \in \mathbb{R}^{\#\sigma \times k}$$

$$M_{\tau,\sigma} = \mathcal{U}_\tau \cdot S_{\tau,\sigma} \cdot \mathcal{V}_\sigma^H$$

with

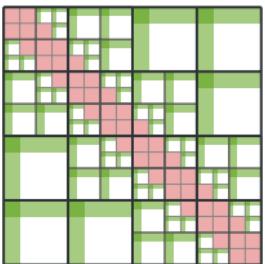
$$\begin{aligned} \mathcal{U}_\tau &\in \mathbb{R}^{\#\tau \times k}, \mathcal{V}_\sigma \in \mathbb{R}^{\#\sigma \times k}, \\ S_{\tau,\sigma} &\in \mathbb{R}^{k \times k} \end{aligned}$$

$$\mathcal{O}(n \log n)$$

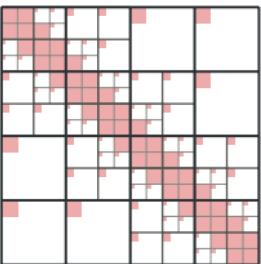
$$\underline{\mathcal{O}(n)} + \mathcal{O}(n \log n)$$

Basis Representation

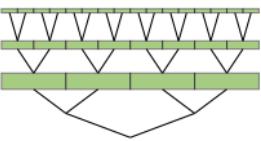
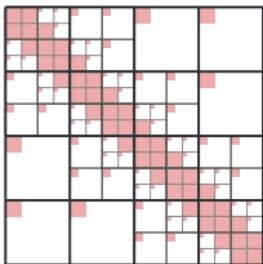
Separate Bases



Shared Bases



Nested Bases



$$M_{\tau,\sigma} = U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$$

with

$$U_{\tau,\sigma} \in \mathbb{R}^{\#\tau \times k}, V_{\tau,\sigma} \in \mathbb{R}^{\#\sigma \times k}$$

$$\mathcal{O}(n \log n)$$

$$M_{\tau,\sigma} = \mathcal{U}_\tau \cdot S_{\tau,\sigma} \cdot \mathcal{V}_\sigma^H$$

with

$$\begin{aligned} \mathcal{U}_\tau &\in \mathbb{R}^{\#\tau \times k}, \mathcal{V}_\sigma \in \mathbb{R}^{\#\sigma \times k}, \\ S_{\tau,\sigma} &\in \mathbb{R}^{k \times k} \end{aligned}$$

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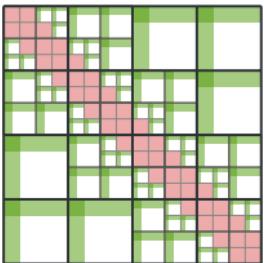
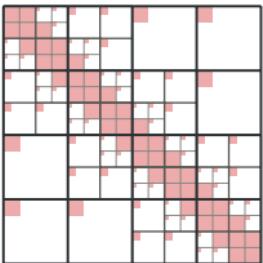
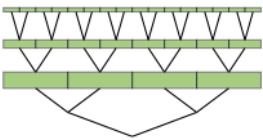
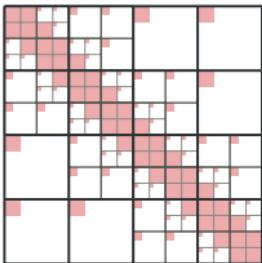
$$M_{\tau,\sigma} = \tilde{\mathcal{U}}_\tau \cdot S_{\tau,\sigma} \cdot \tilde{\mathcal{V}}_\sigma^H$$

with

$$\textcolor{red}{implicit} \quad \tilde{\mathcal{U}}_\tau, \tilde{\mathcal{V}}_\sigma$$

$$\mathcal{O}(n)$$

Basis Representation

 \mathcal{H} Uniform- \mathcal{H}  \mathcal{H}^2 

$$M_{\tau,\sigma} = U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$$

with

$$U_{\tau,\sigma} \in \mathbb{R}^{\#\tau \times k}, V_{\tau,\sigma} \in \mathbb{R}^{\#\sigma \times k}$$

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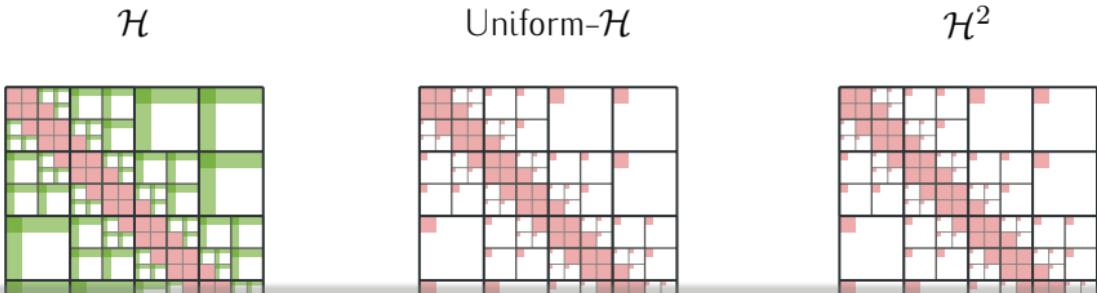
$$M_{\tau,\sigma} = \tilde{\mathcal{U}}_\tau \cdot S_{\tau,\sigma} \cdot \tilde{\mathcal{V}}_\sigma^H$$

with

implicit $\tilde{\mathcal{U}}_\tau, \tilde{\mathcal{V}}_\sigma$

$$\mathcal{O}(n)$$

Basis Representation



Definition 2.11. Let $V_k = V_k(I \times I)$ as before and deduce from V_k the subspaces $V_k(b)$ for all blocks $b \in P_2$. An \mathcal{H} -matrix from $\mathcal{M}_{\mathcal{H},k}(I \times I, P_2)$ is a uniform \mathcal{H} -matrix, if all block matrices M^b , $b \in P_2$, appearing in (7) belong to $V_k(b)$. The set of uniform \mathcal{H} -matrices is denoted by $\mathcal{U}_{\mathcal{H},k}(I \times I, P_2, V_k)$.

Hackbusch: "A Sparse Matrix Arithmetic Based on \mathcal{H} -Matrices. Part I: Introduction to \mathcal{H} -Matrices", Computing 62, 89–108, 1999.

with

$$U_{\tau,\sigma} \in \mathbb{R}^{\#\tau \times k}, V_{\tau,\sigma} \in \mathbb{R}^{\#\sigma \times k}$$

with

$$\mathcal{U}_\tau \in \mathbb{R}^{\#\tau \times k}, \mathcal{V}_\sigma \in \mathbb{R}^{\#\sigma \times k},$$

$$S_{\tau,\sigma} \in \mathbb{R}^{k \times k}$$

with

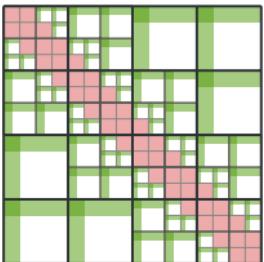
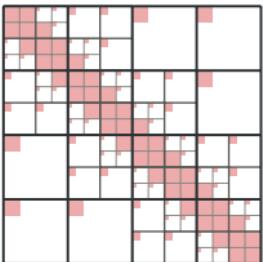
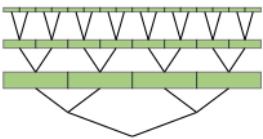
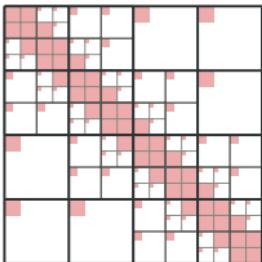
$$\text{implicit } \tilde{\mathcal{U}}_\tau, \tilde{\mathcal{V}}_\sigma$$

$$\mathcal{O}(n \log n)$$

$$\underline{\mathcal{O}(n)} + \mathcal{O}(n \log n)$$

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Basis Representation

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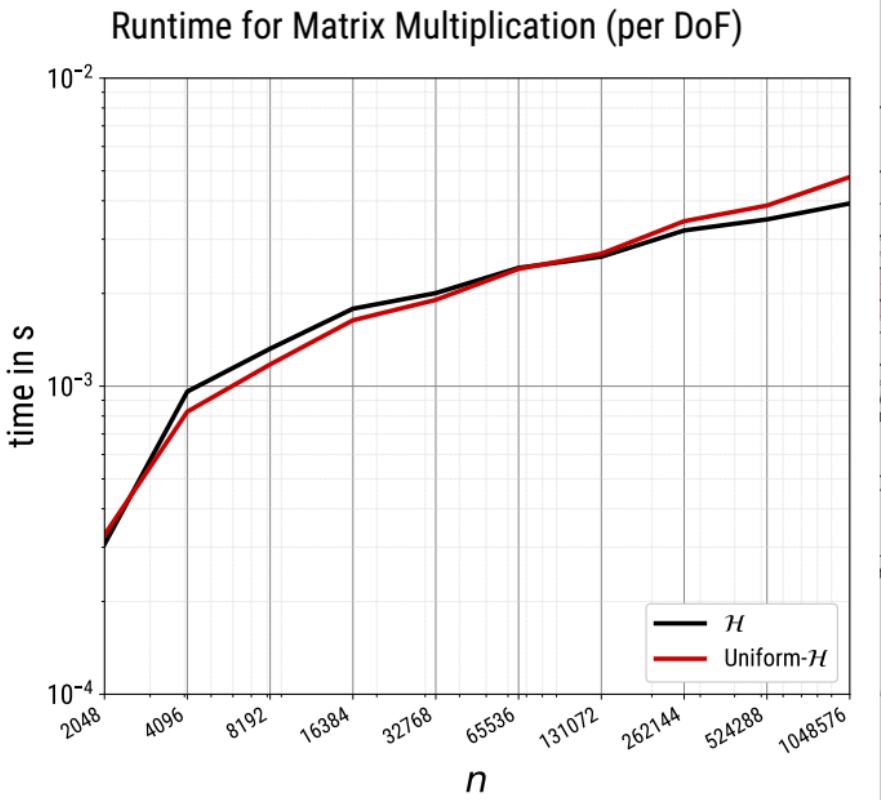
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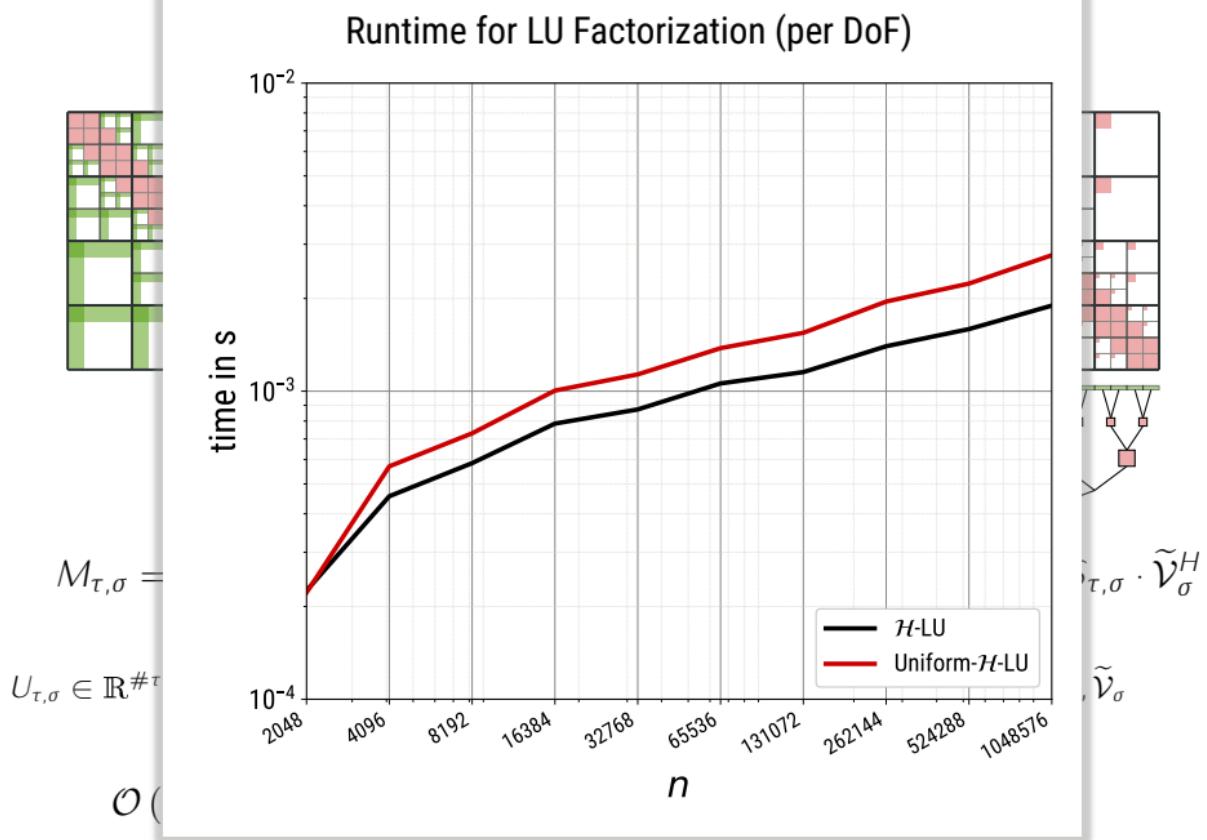
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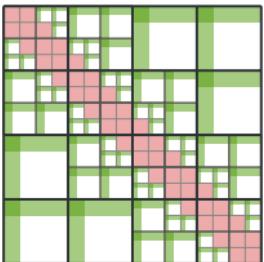
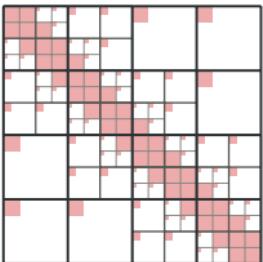
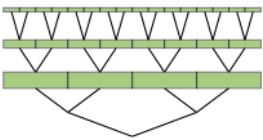
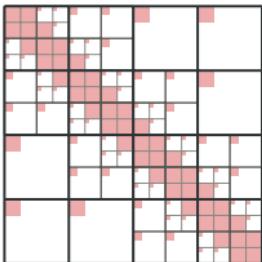
Basis Representation


 $M_{\tau,\sigma} =$
 $U_{\tau,\sigma} \in \mathbb{R}^{\# \tau}$
 $\mathcal{O}($

 $\mathcal{V}_{\tau,\sigma} \cdot \tilde{\mathcal{V}}_{\sigma}^H$
 $\tilde{\mathcal{V}}_{\sigma}$

Basis Representation



Basis Representation

 \mathcal{H} Uniform- \mathcal{H}  \mathcal{H}^2 

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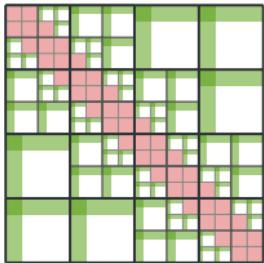
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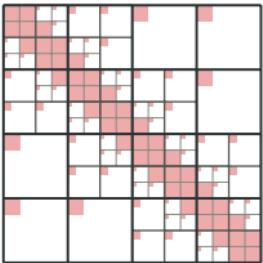
$$\mathcal{O}(n)$$

Basis Representation

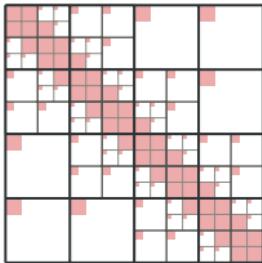
\mathcal{H}



Uniform- \mathcal{H}



\mathcal{H}^2



$M = \mathcal{U} \cup \mathcal{V}^H$

$M = \mathcal{U} \cup \mathcal{S} \cup \mathcal{V}^H$

$M = \widetilde{\mathcal{U}} \cup \mathcal{S} \cup \widetilde{\mathcal{V}}^H$

How do we *store* the data blocks (**dense** and **lowrank**)?

$$\mathcal{O}(n \log n)$$

$$\underline{\mathcal{O}(n)} + \mathcal{O}(n \log n)$$

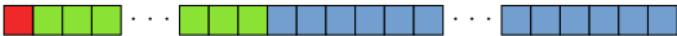
$$\mathcal{O}(n)$$

NUMBER REPRESENTATION

Number Representation

For scientific computations almost always the IEEE-754 floating point standard is used.

- one sign bit
- e exponent bits and
- m mantissa bits



The mantissa bits define the floating point accuracy with *unit roundoff*

$$u = 2^{-(m+1)}$$

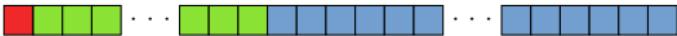
Most common formats:

	s-e-m	Bits	Unit Roundoff
FP80	1-15-64	80	2.7×10^{-20}
FP64	1-11-52	64	1.1×10^{-16}
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However, often lowrank approximation is much coarser than the unit roundoff:

$$\varepsilon \gg u$$

Number Representation

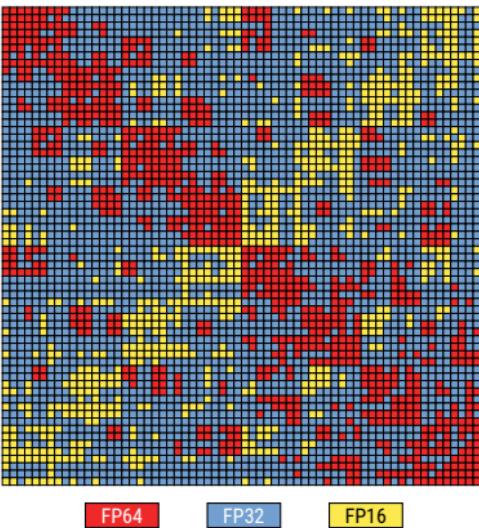
In recent years, more floating point formats were added to IEEE-754:

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FP80	1-15-64	80	2.7×10^{-20}
FP64	1-11-52	64	1.1×10^{-16}
FP32	1-8-23	32	6.0×10^{-8}
TF32	1-8-10	19	4.9×10^{-4}
FP16	1-5-10	16	4.9×10^{-4}
BF16	1-8-7	16	3.9×10^{-3}
FP8	1-4-3	8	6.2×10^{-2}

How can we use these formats for storing matrix data?

Mixed Precision within Matrix¹

Choose precision of lowrank block $U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$ based on $\|M_{\tau,\sigma}\|$.



Dense blocks always stored in FP64.

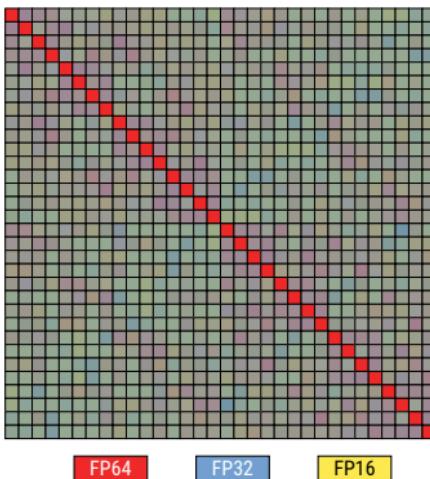
¹Abdulah, Cao, Pei, Bosilca, Dongarra, Genton, Keyes, Ltaief, Sun: "Accelerating Geostatistical Modeling and Prediction With Mixed-Precision Computations: A High-Productivity Approach With PARSEC", IEEE Trans. on Par. and Distr. Systems, 2022

Mixed Precision within Lowrank Block^{1,2}

Represent $U_{\tau,\sigma} \cdot V_{\tau,\sigma}^H$ as

$$W \cdot \Sigma \cdot X^H = [W_1 W_2 W_3] \cdot \text{diag}(\Sigma_1, \Sigma_2, \Sigma_3) \cdot [X_1 X_2 X_3]^H$$

with orthogonal W, X and splitting depending on the singular values σ_j in Σ_i .

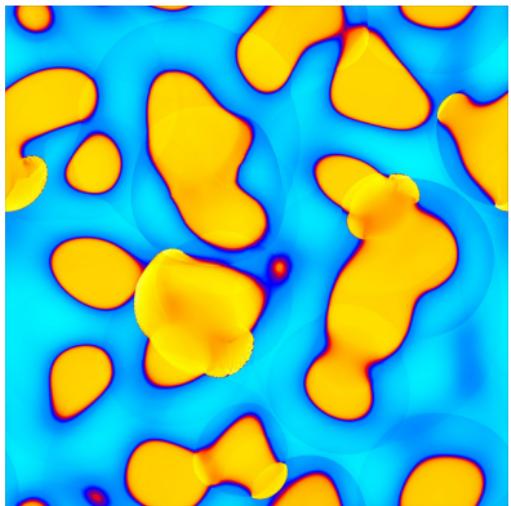


¹Ooi, Iwashita, Fukaya, Ida, Yokota.: "Effect of Mixed Precision Computing on H-Matrix Vector Multiplication in BEM Analysis", Proceedings of HPCAsia2020, 2020

²Amestoy, Boiteau, Buttari, Gerest, Jézéquel, L'Excellent, Mary: "Mixed precision low-rank approximations and their application to block low-rank LU factorization", IMA J. of Num. Analysis, 2022

Floating Point Compression

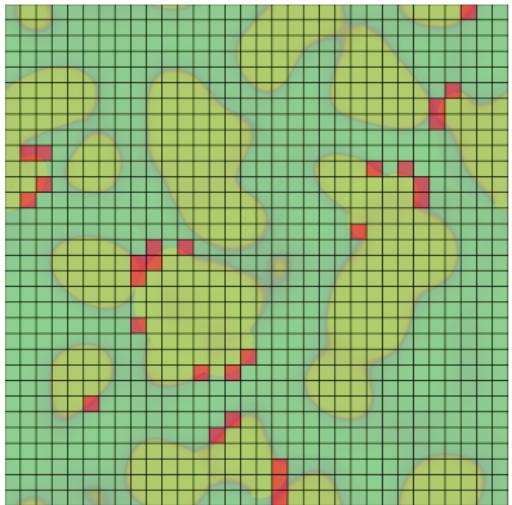
For a combustion application, lowrank approximation was combined with (lossy) floating point compression to minimize data storage¹:



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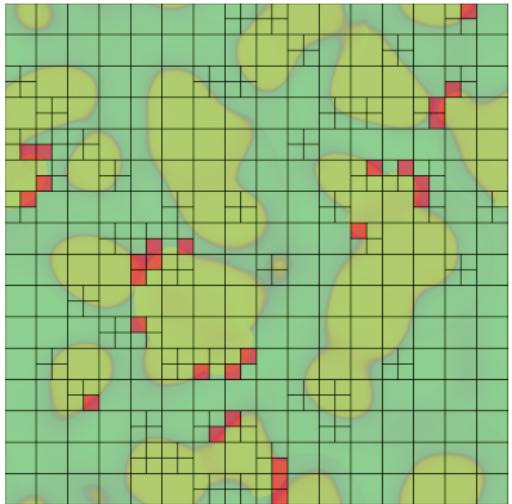
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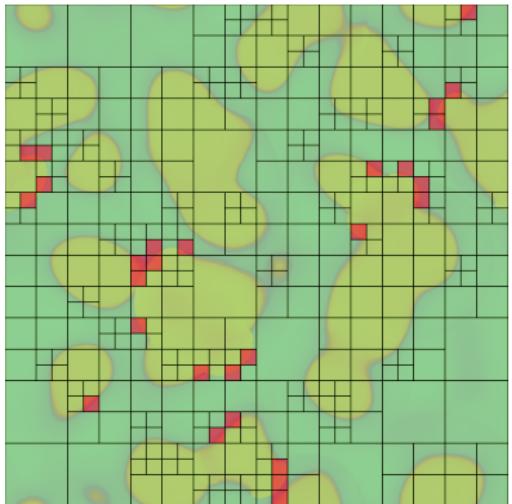
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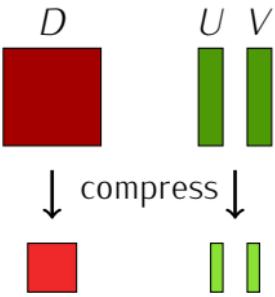
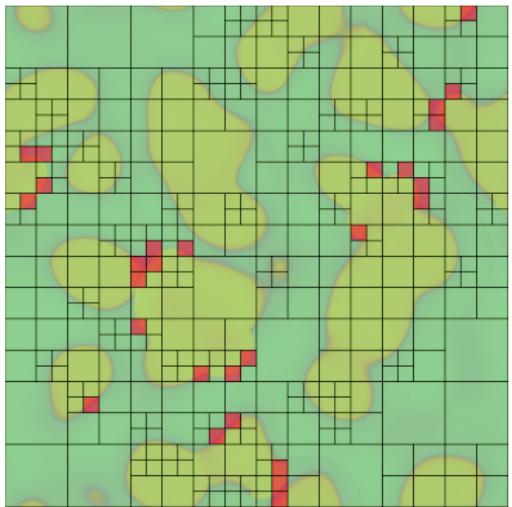
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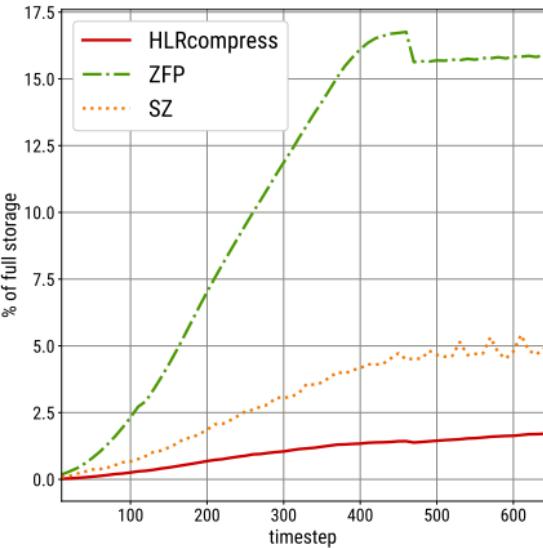
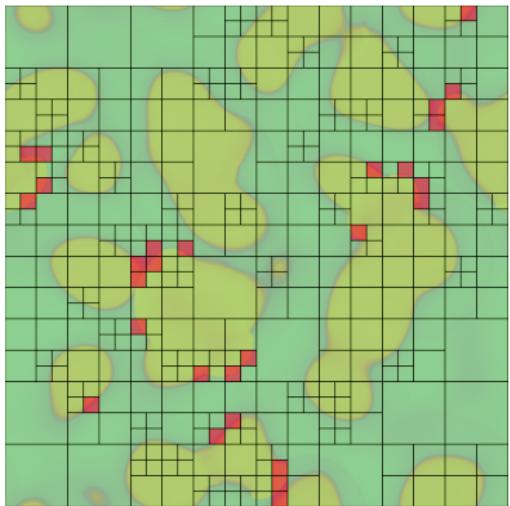
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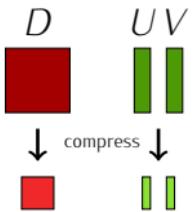


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Floating Point Compression

Directly compress data blocks $D_{\tau,\sigma}$ from dense blocks and $U_{\tau,\sigma}, V_{\tau,\sigma}$ from lowrank blocks using floating point compression schemes.

Assumption: compression scheme has *error control*.



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Assumption: compression scheme has *error control*.

ZFP¹

- bitplane truncation for 4^d blocks,

BLOSC⁴

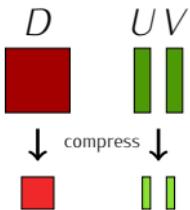
- bit shuffling plus lossless compression,
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SZ²/SZ3³

- uses curve fitting via splines,

MGARD⁵

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²Di, Cappello: "Fast Error-Bounded Lossy HPC Data Compression with SZ", IEEE IPDPS. pp. 730–739 (2016)

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⁴<https://blosc.org>

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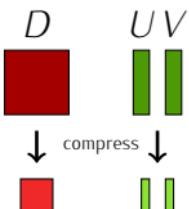
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ZFP¹

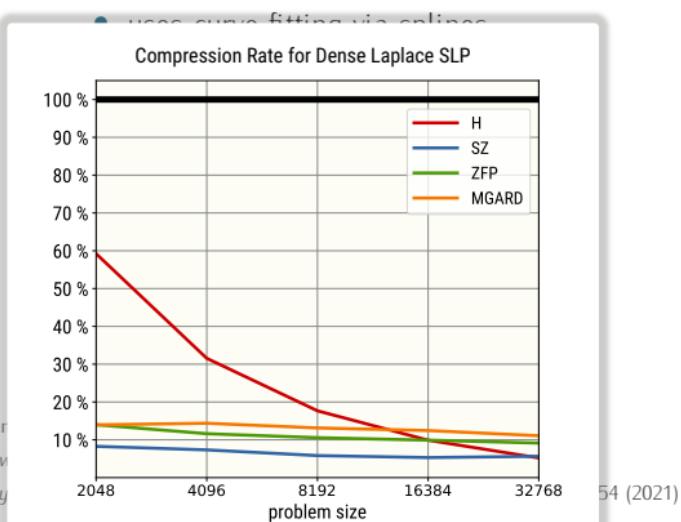
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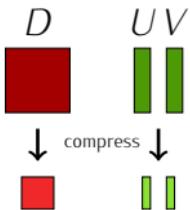
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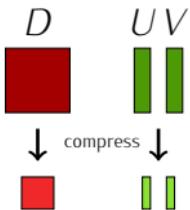
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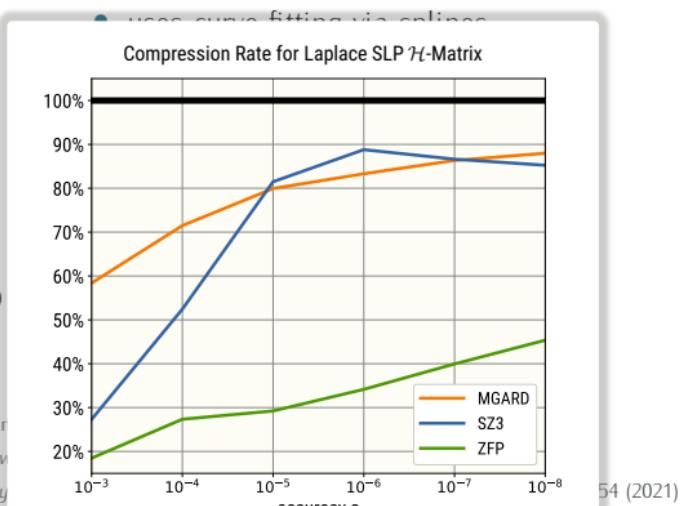
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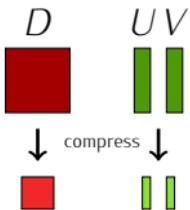
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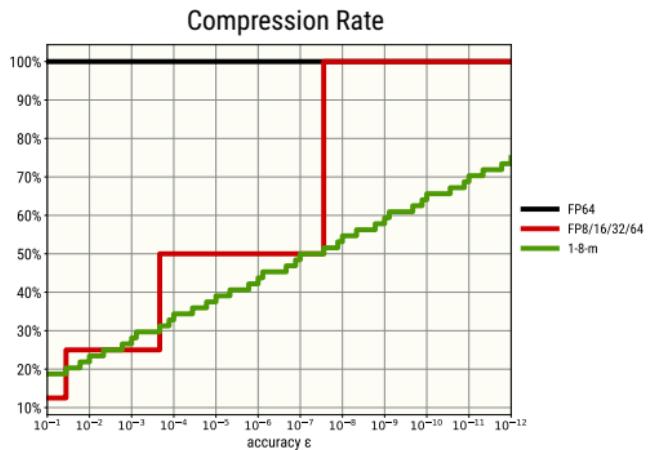
Floating Point Compression

Compression also possible within IEEE-754 scheme by choosing

- mantissa bits m based on accuracy

	s-e-m	u	Range ¹
FP64	1-11-52	$1 \cdot 10^{-16}$	631
FP32	1-8-23	$6 \cdot 10^{-8}$	83
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BF16	1-8-7	$4 \cdot 10^{-3}$	78
FP16	1-5-10	$5 \cdot 10^{-4}$	12
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¹Dynamic range as $\log_{10} \frac{v_{\max}}{v_{\min}}$



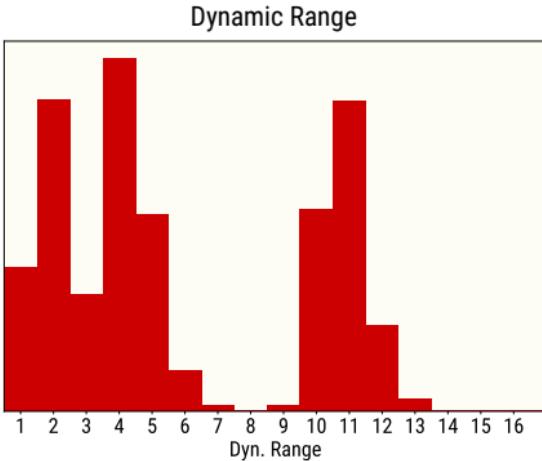
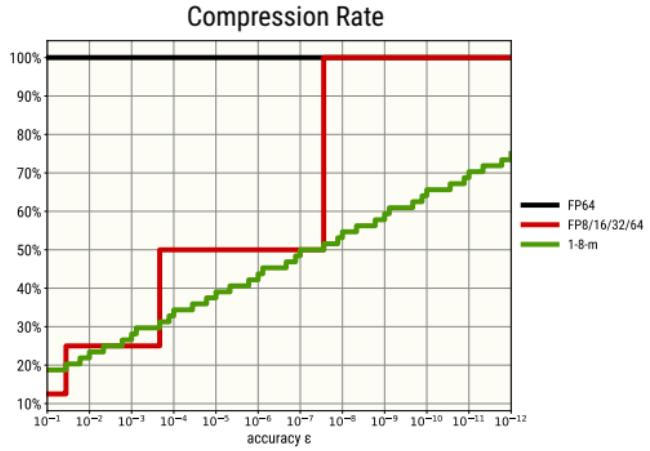
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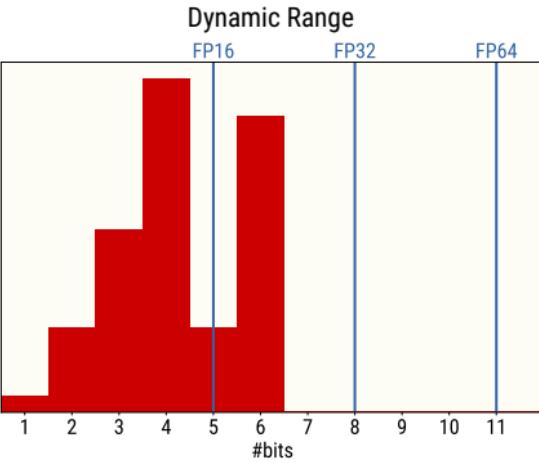
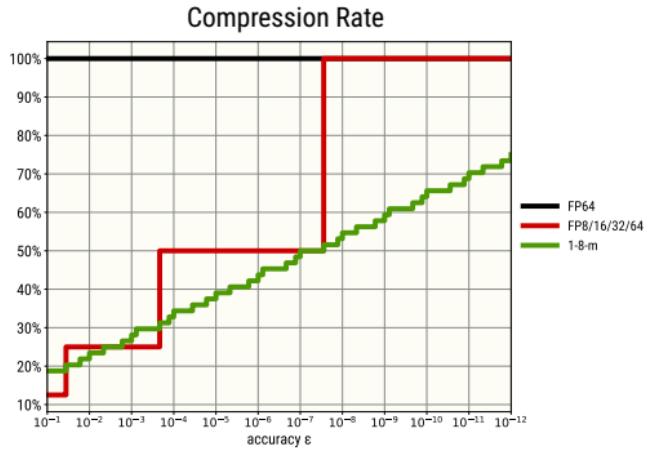
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AFL:

- fully adaptive choice of m and e ,
- use 1-e-m to store data (with scaling and shifting),
- *slow* bit stream storage.



AFLP:

- choose e and m as in AFL,
- increase m such that $1 + e + m$ is multiple of 8



ADAPTIVE PRECISION FOR LOW-RANK DATA

Adaptive Precision for Low-Rank Data

Given $\|M_{\tau,\sigma} - U_{\tau,\sigma}V_{\tau,\sigma}^H\| \leq \delta$ and p floating point formats and

$$U_{\tau,\sigma}V_{\tau,\sigma}^H = W\Sigma X^H = (W_1 \dots W_p) \begin{pmatrix} \Sigma_1 & & \\ & \ddots & \\ & & \Sigma_p \end{pmatrix} (X_1 \dots X_p)^H$$

with unit roundoffs u_1, \dots, u_p such that

$$\|\Sigma_i\| \leq \frac{\delta}{u_i}$$

Let $\tilde{M}_{\tau,\sigma}$ be the representation of $M_{\tau,\sigma}$ where W_i, X_i are stored in the i 'th floating point format. Then the error $\|M_{\tau,\sigma} - \tilde{M}_{\tau,\sigma}\|$ is bounded by¹

$$\|M_{\tau,\sigma} - \tilde{M}_{\tau,\sigma}\| \leq \delta + \left(2(p-1) + \sum_{i=2}^p \sqrt{k_i} u_i \right) \delta$$

¹Amestoy, Boiteau, Buttari, Gerest, Jézéquel, L'Excellent, Mary: "Mixed precision low-rank approximations and their application to block low-rank LU factorization", IMA J. of Num. Analysis, 2022

Adaptive Precision for Low-Rank Data

Replace the predefined IEEE-754 formats by a general compression scheme with adaptive error control.

Adaptive Precision for Low-Rank (APLR)

For all columns (w_i, x_i) of W/X choose precision \tilde{u}_i such that

$$\tilde{u}_i = \frac{\delta}{\sigma_i}$$

The error $\|M_{\tau,\sigma} - \tilde{M}_{\tau,\sigma}\|$ becomes

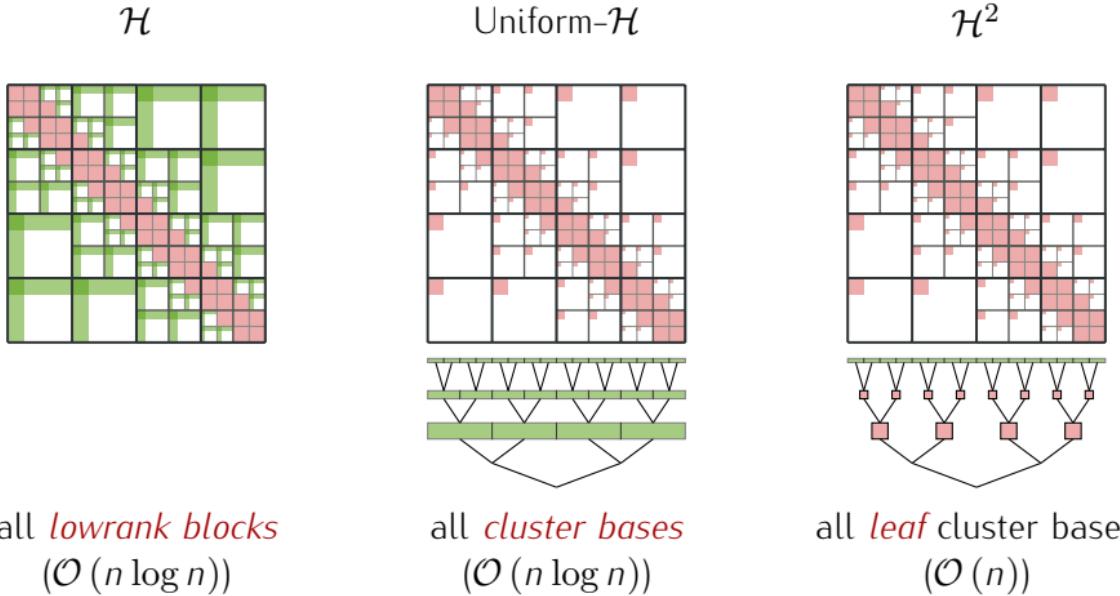
$$\|M_{\tau,\sigma} - \tilde{M}_{\tau,\sigma}\| \leq \delta + 2k\delta + \delta^2 \sum_{i=1}^k \frac{1}{\sigma_i}$$

Remark

Dense matrix blocks are directly compressed.

Adaptive Precision for Low-Rank Data

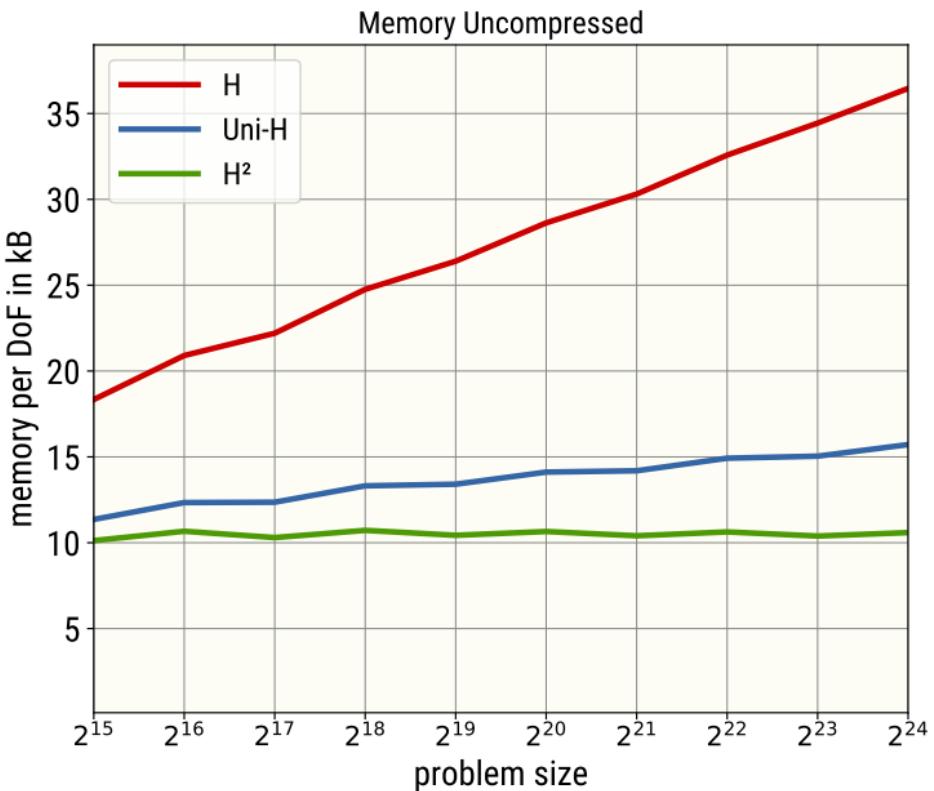
Depending on the \mathcal{H} -matrix format, APLR can be applied to different data.



For everything else, standard compression can be applied.

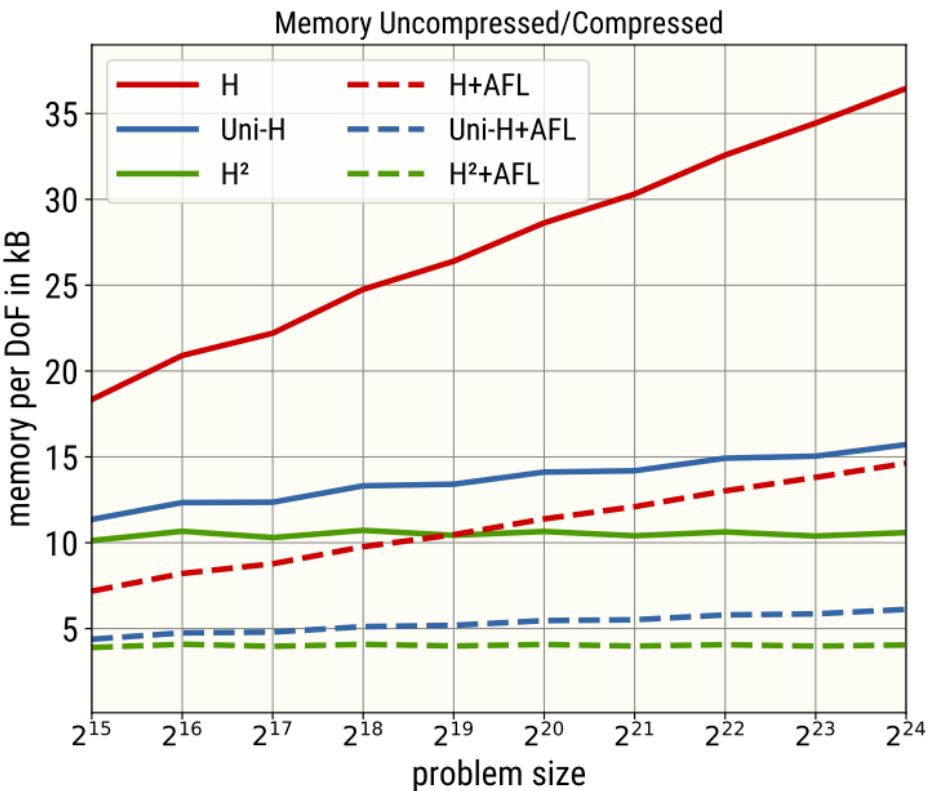
Adaptive Precision for Low-Rank Data

Laplace SLP ($\varepsilon = 10^{-6}$)



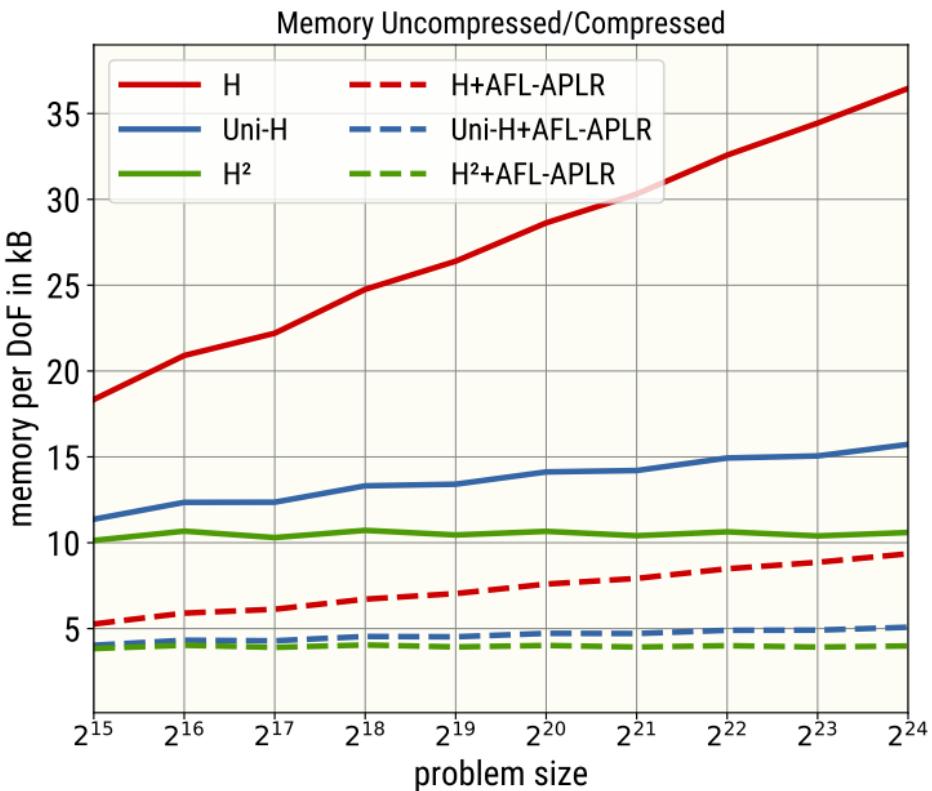
Adaptive Precision for Low-Rank Data

Laplace SLP ($\varepsilon = 10^{-6}$, AFL)



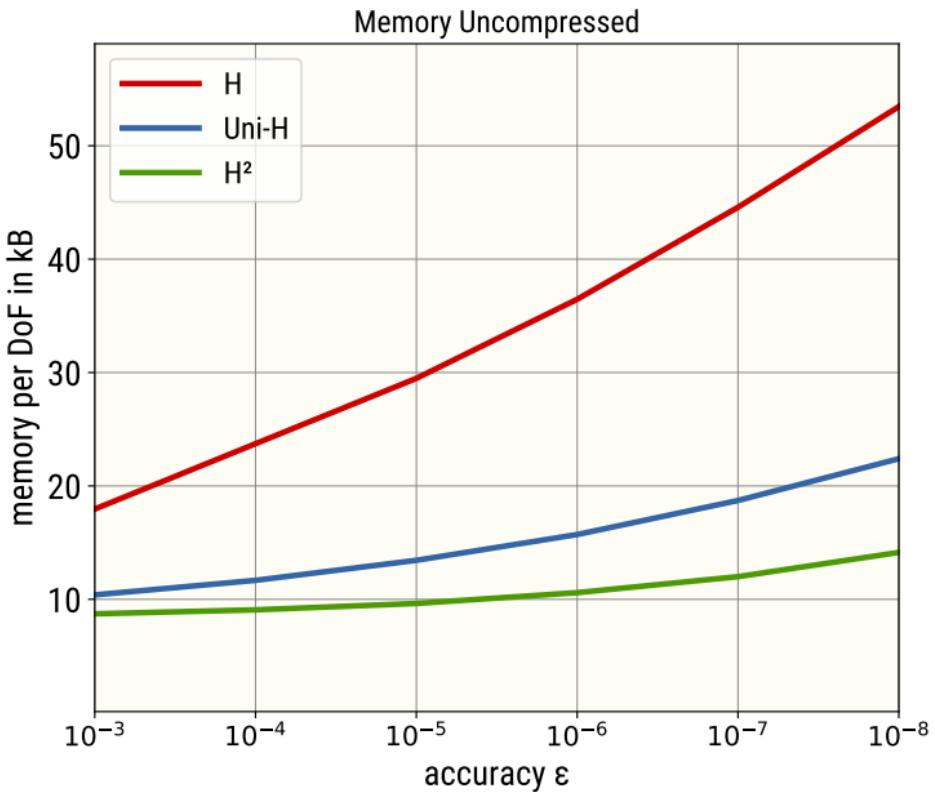
Adaptive Precision for Low-Rank Data

Laplace SLP ($\varepsilon = 10^{-6}$, AFL+APLR)



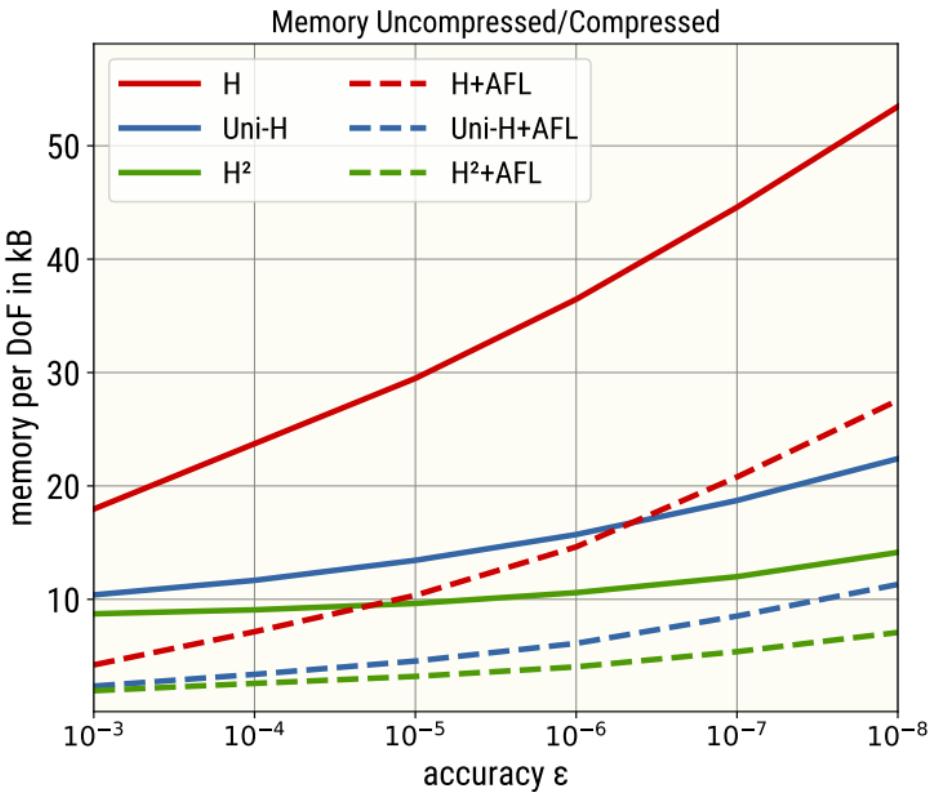
Adaptive Precision for Low-Rank Data

Laplace SLP ($n = 16.777.216$)



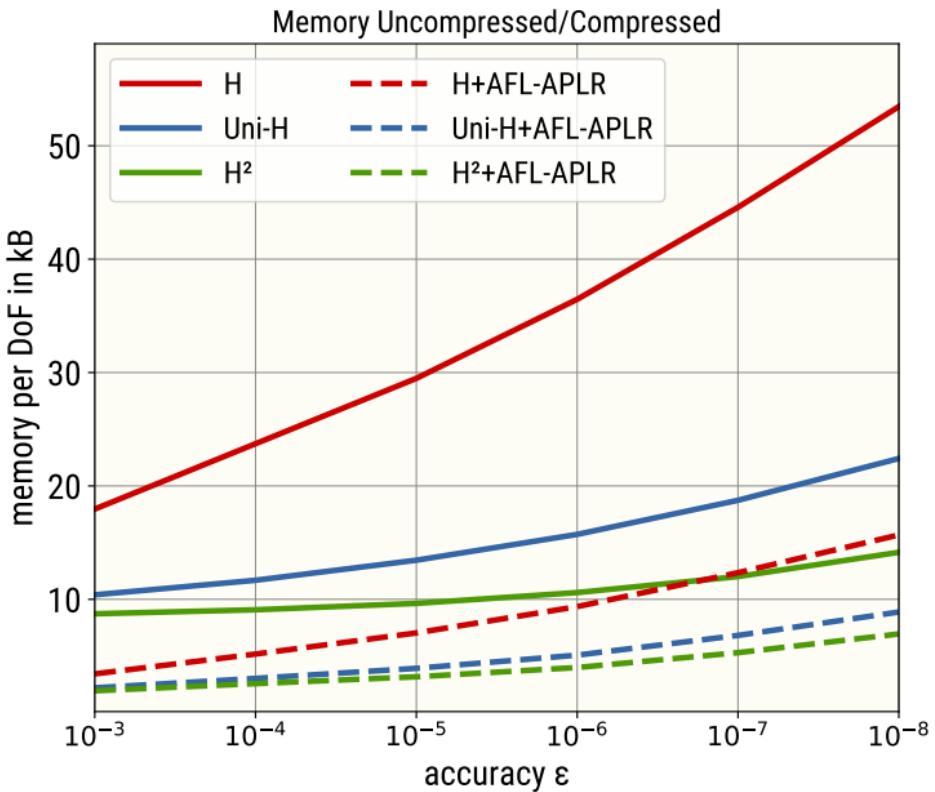
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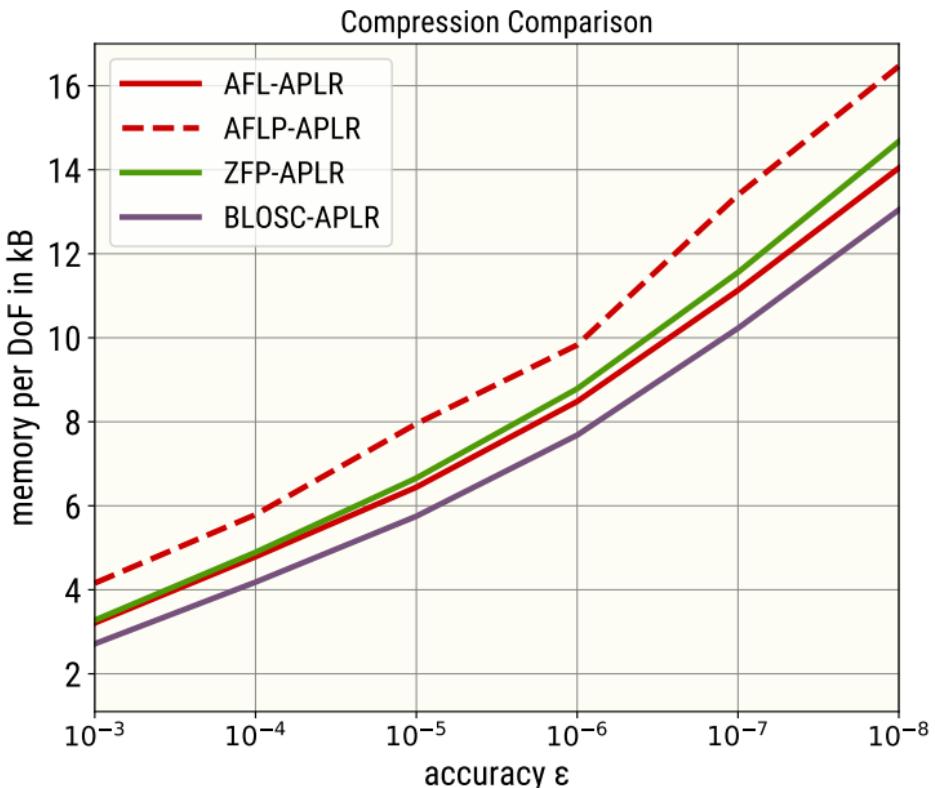
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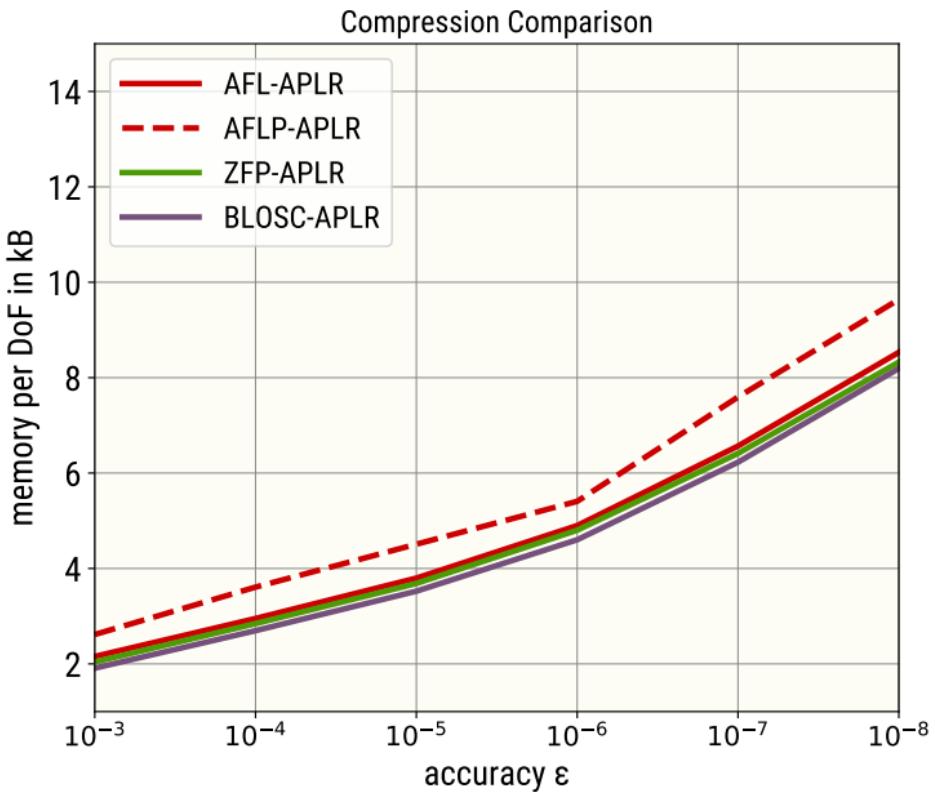
Adaptive Precision for Low-Rank Data

Laplace SLP ($n = 1.048.576$, X +APLR, \mathcal{H})



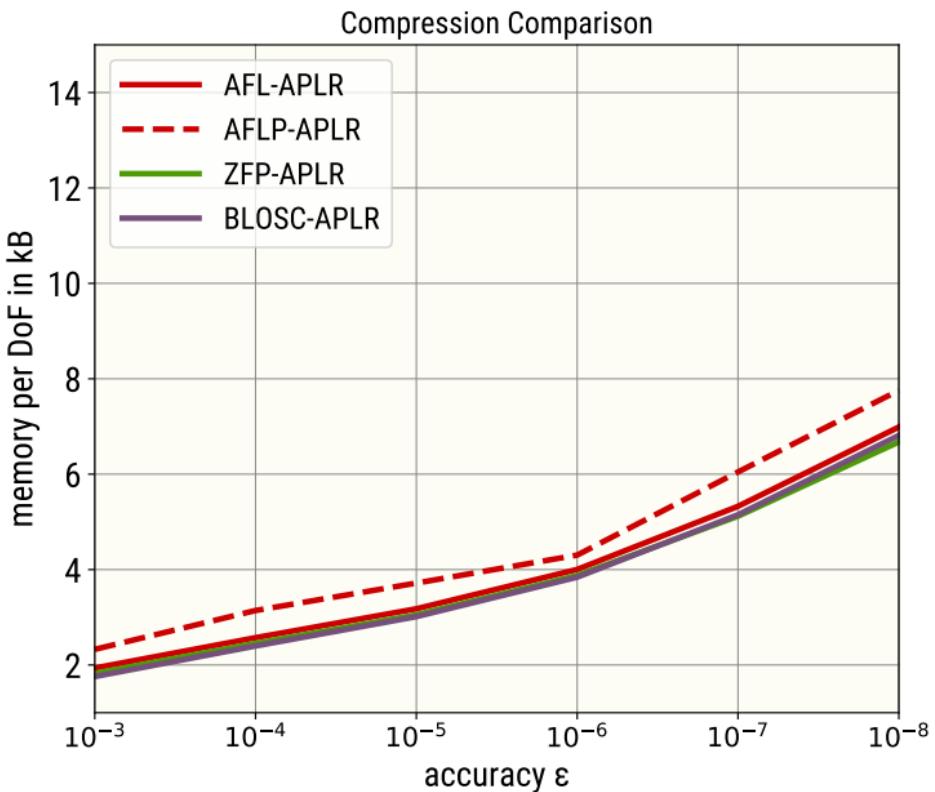
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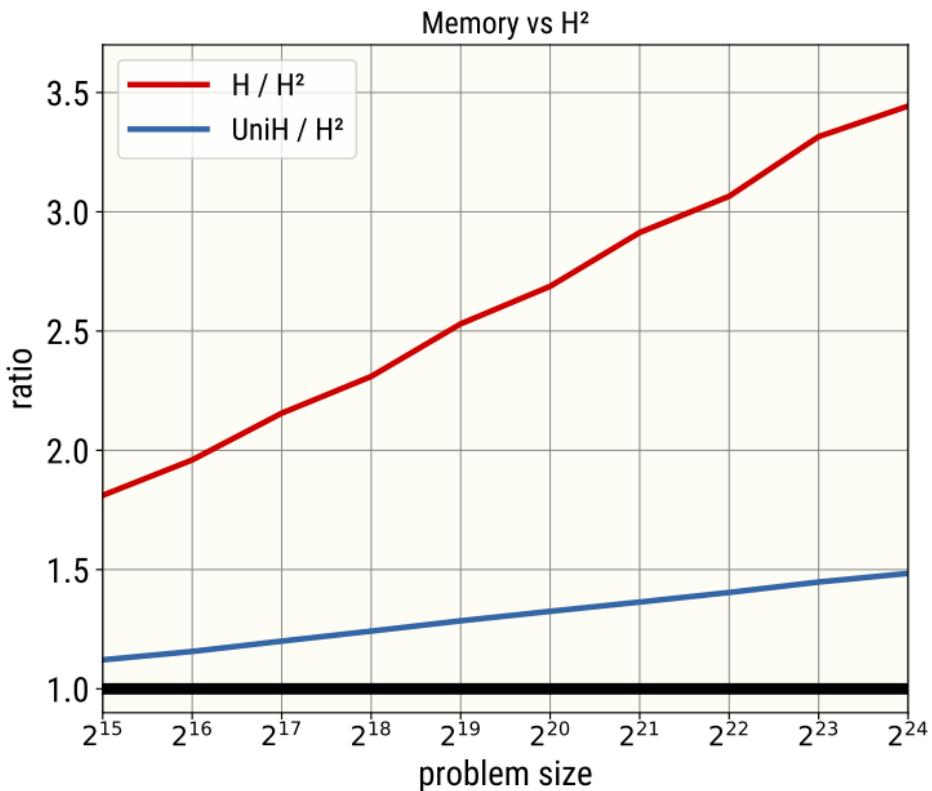
Adaptive Precision for Low-Rank Data

Laplace SLP ($n = 1.048.576$, $X + \text{APLR}$, \mathcal{H}^2)



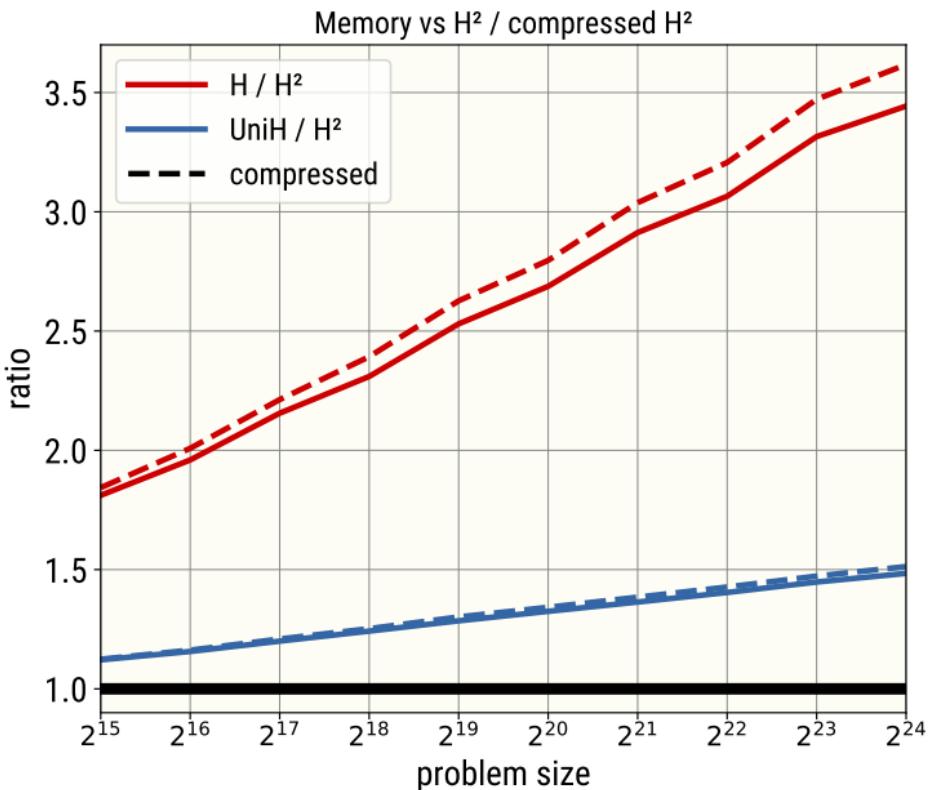
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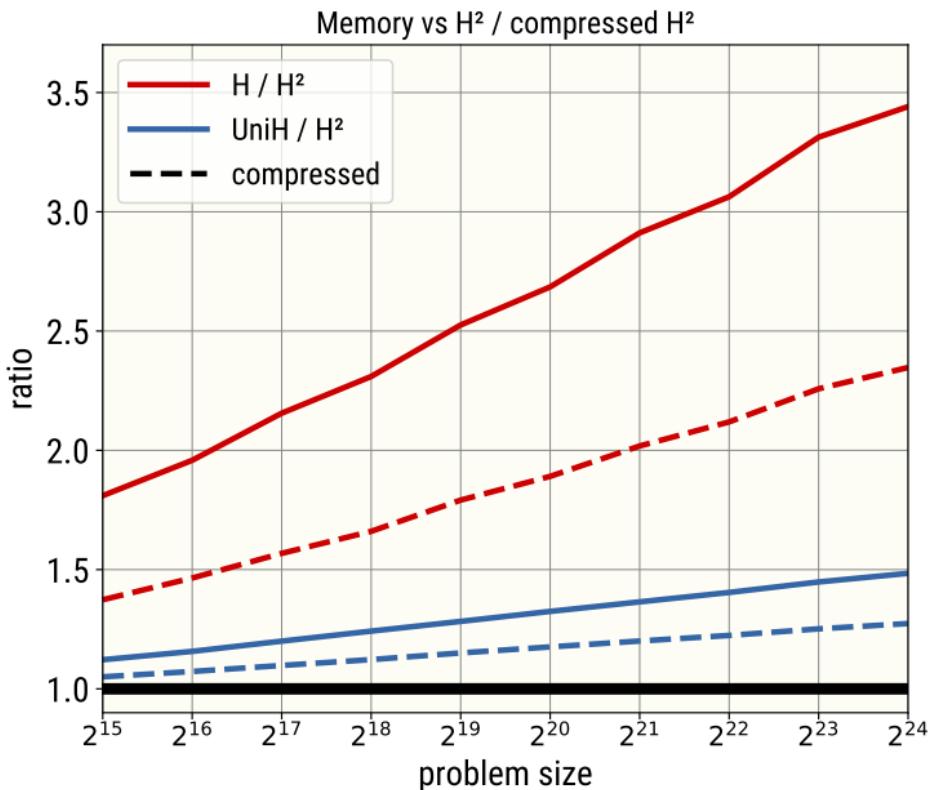
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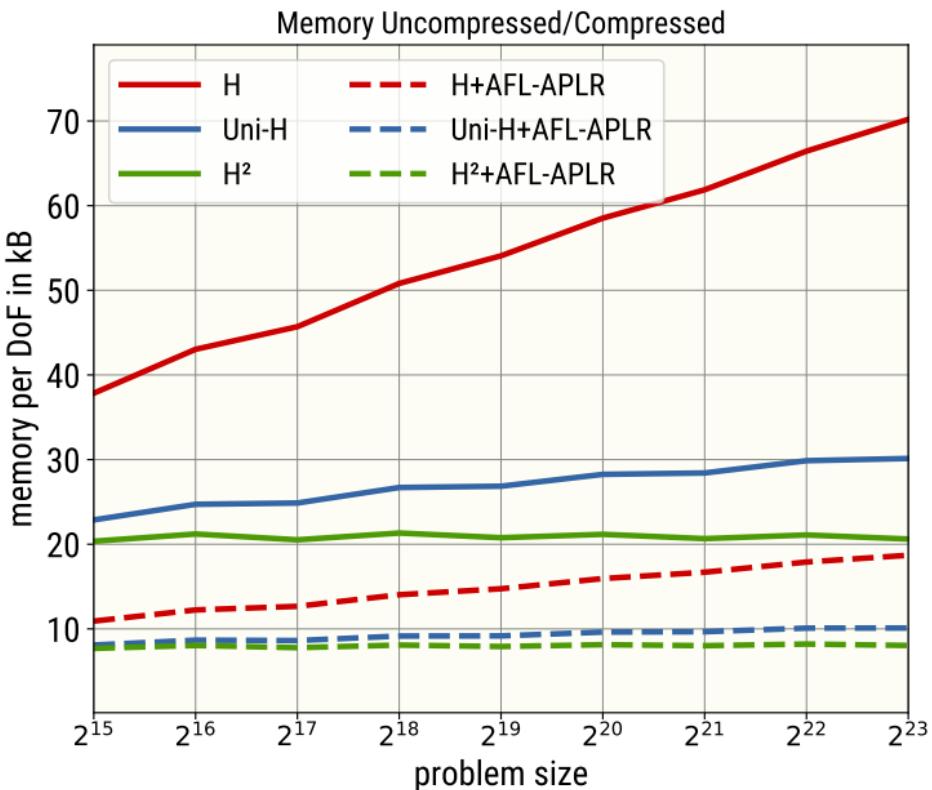
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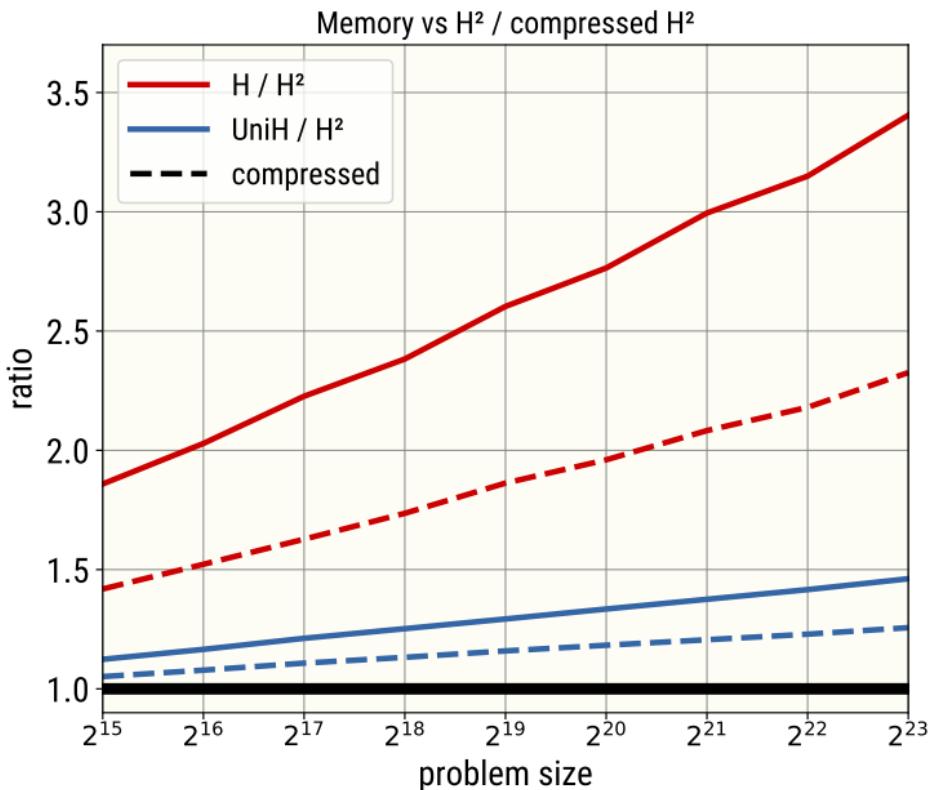
Adaptive Precision for Low-Rank Data

Helmholtz SLP ($\varepsilon = 10^{-6}$, $\kappa = 2$, AFL+APLR)



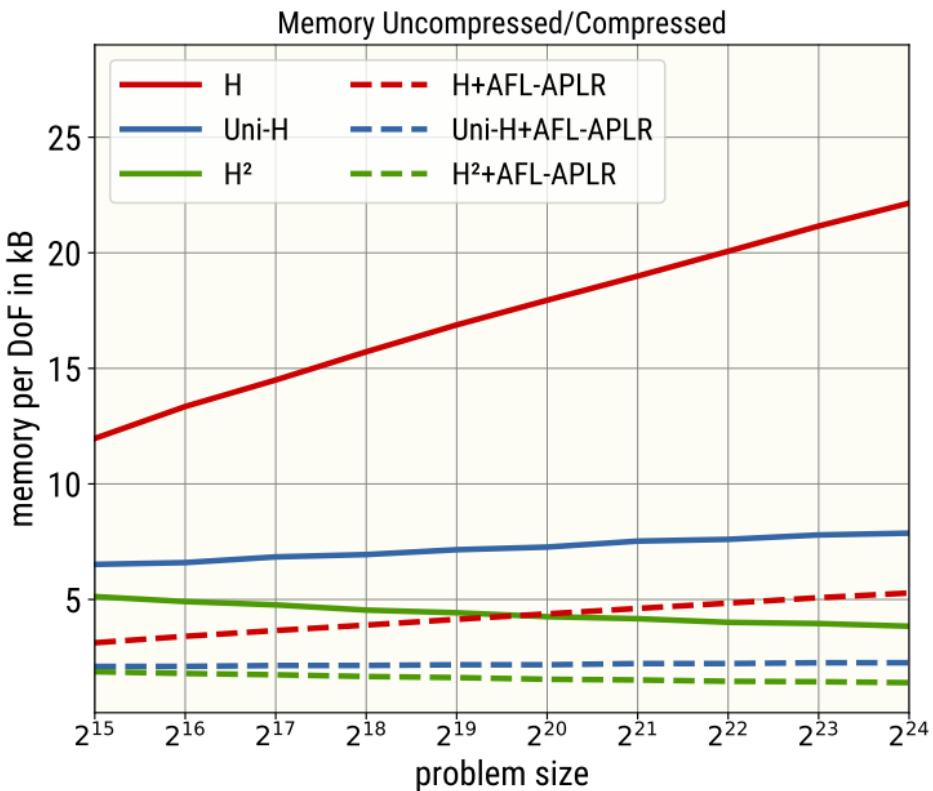
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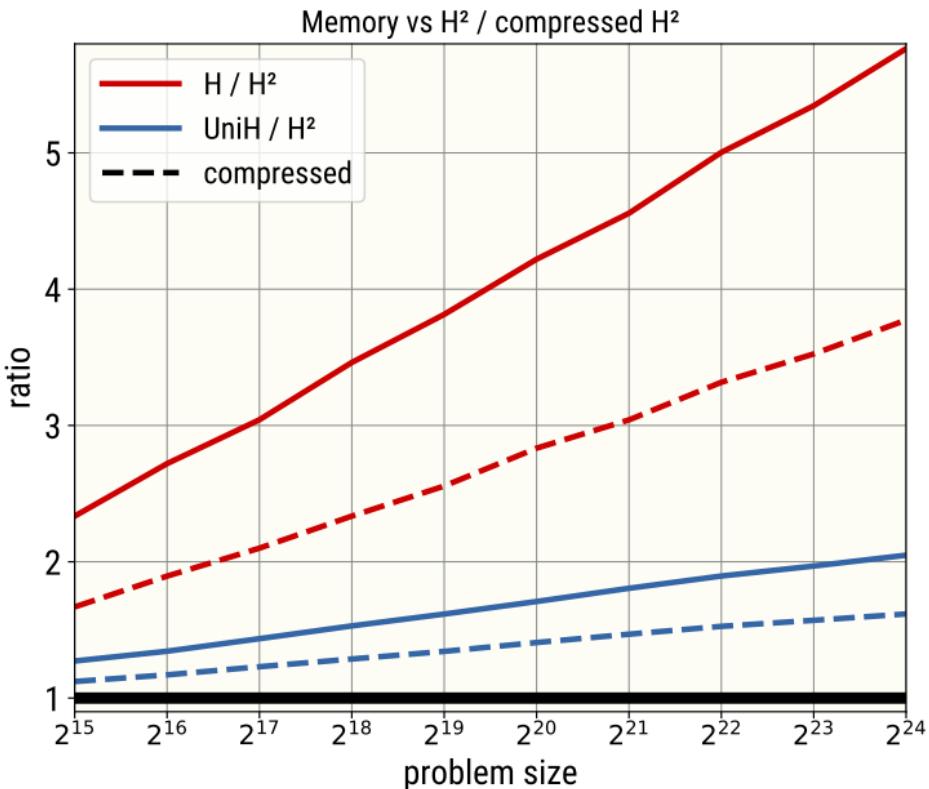
Adaptive Precision for Low-Rank Data

Matérn Covariance ($\varepsilon = 10^{-6}$, AFL+APLR)



Adaptive Precision for Low-Rank Data

Matérn Covariance ($\varepsilon = 10^{-6}$, AFL+APLR)



\mathcal{H} -ARITHMETIC

Decoupling of storage and compute precision¹:

- compression only for storage,
- all computations in FP64.

Use *function-level* conversion due to BLAS/LAPACK based arithmetic.

```
function MVM(in: U, V, x, inout: y)
    V_d := decompress(V);
    t := V_d^H x;
    U_d := decompress(U);
    y := y + U_d t;
```

```
function TRUNCATE(in: U, V, ε, out: W, X)
    U_d := decompress(U);
    V_d := decompress(V);
    [Q_U, R_U] := qr( U_d );
    [Q_V, R_V] := qr( V_d );
    [U_s, S_s, V_s] := svd( R_U · R_V^H );
    k := rank(S_s, ε);
    W_d := Q_U · U_s(:, 1:k) · S_s(1:k, 1:k);
    X_d := Q_V · V_s(:, 1:k);
    W := compress(W_d);
    X := compress(X_d);
```

¹Anzt, Flegar, Grützmacher, Quintana-Ortí: "Toward a modular precision ecosystem for high-performance computing", Int. J. of HPC Applications, 33(6), 1069–1078, 2019.

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Alternative: decompress and compute *on-the-fly* for matrix–vector multiplication.

```
function MVM(in:  $U, V, x$ , inout:  $y$ )
   $V_d := \text{decompress}(V);$ 
   $t := V_d^H x;$ 
   $U_d := \text{decompress}(U);$ 
   $y := y + U_d t;$ 
```

```
function MVM_AFLP(in:  $U, V, x$ , inout:  $y$ )
   $t := 0;$ 
  for  $0 \leq \ell < k$  do
    for  $0 \leq j < m$  do
       $t_\ell := t_\ell + \overline{\text{decompress}(V_{j\ell})} x_j;$ 
  for  $0 \leq \ell < k$  do
    for  $0 \leq i < n$  do
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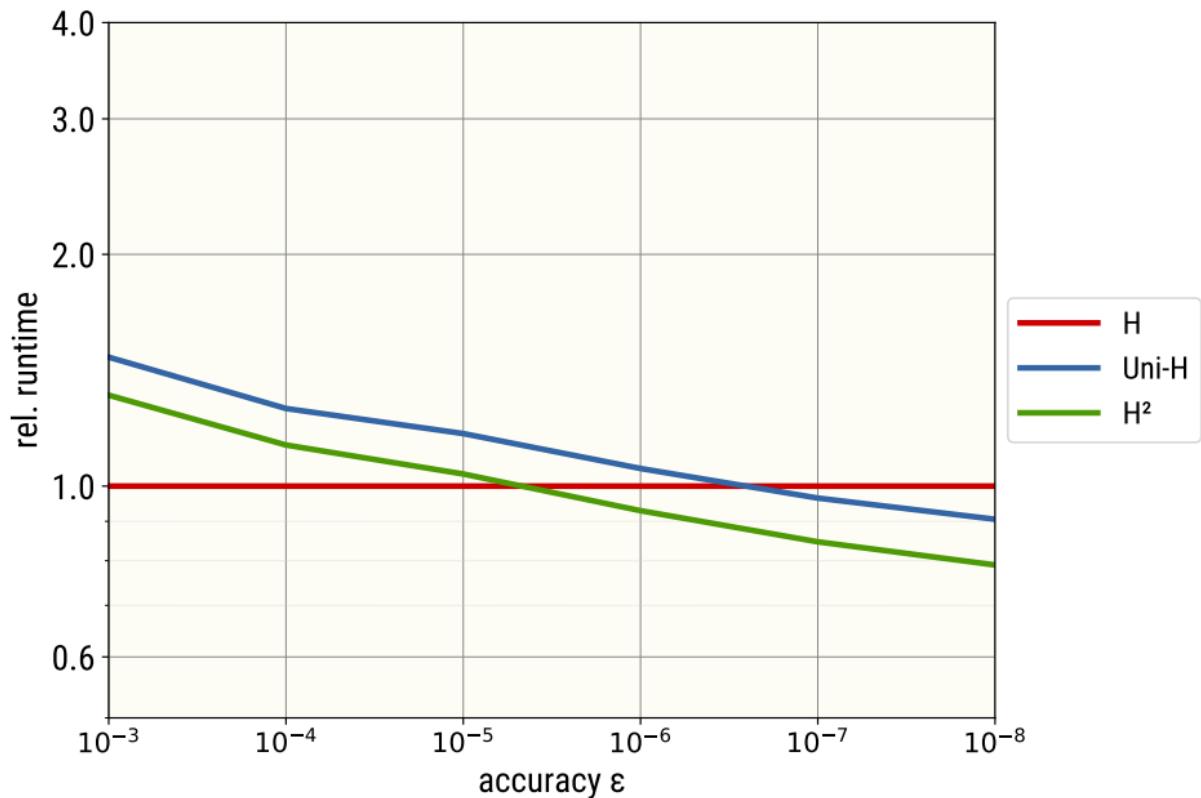
Hardware/Software

- *2x64*-core AMD Epyc 9554 with *2x12* 32GB DDR5-4800 DIMMs
- libHLR + oneTBB + oneMKL (AVX512)

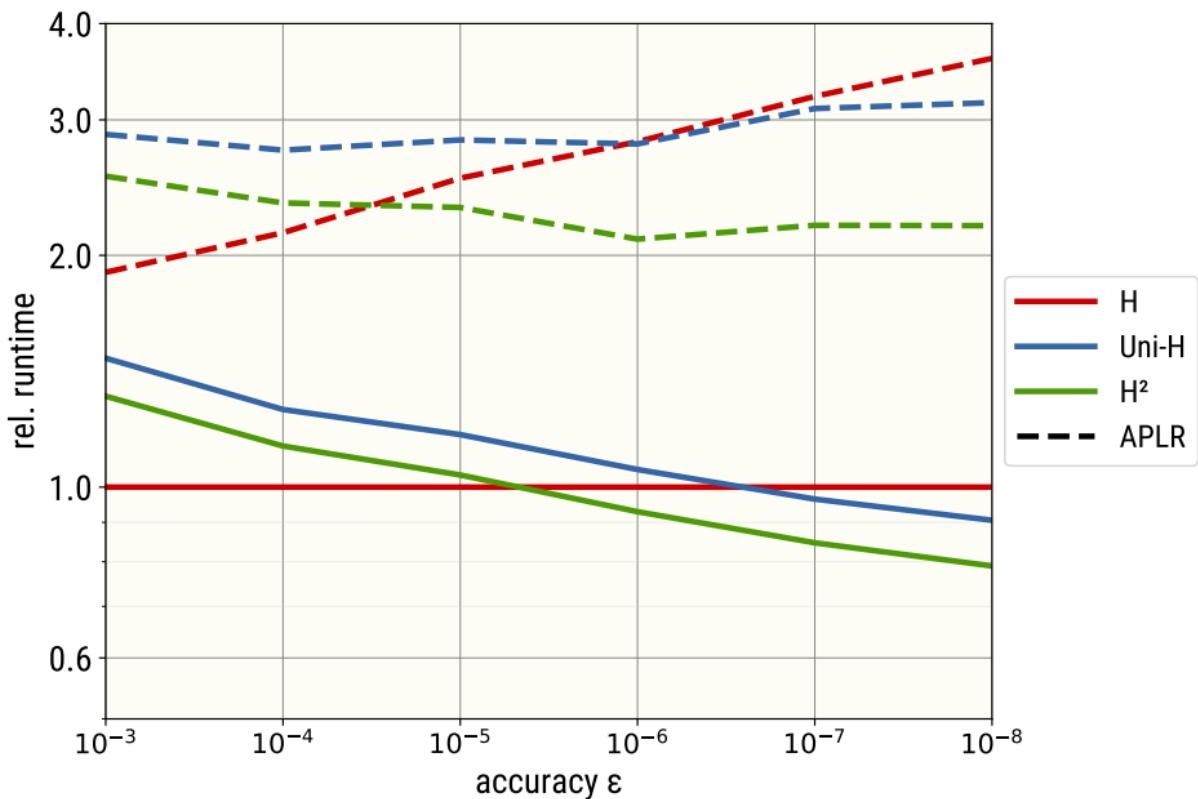
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Matrix-Vector Multiplication

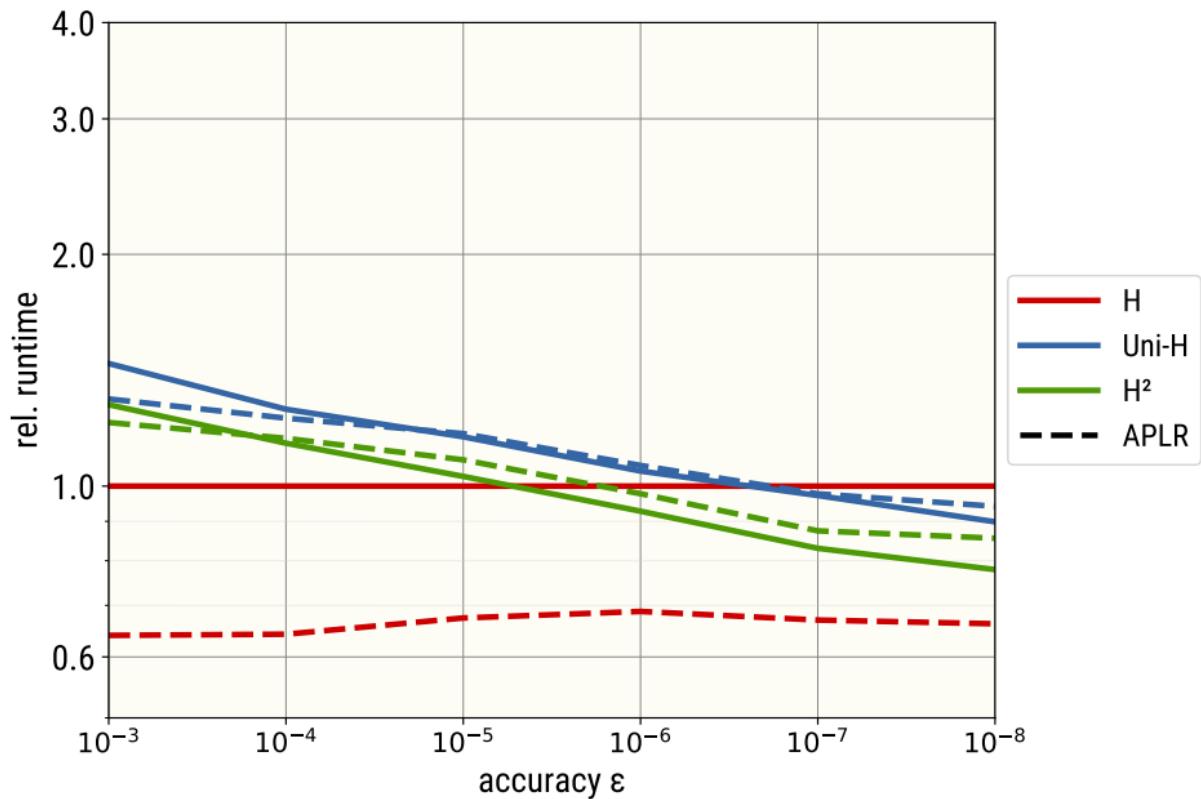
Laplace SLP ($n = 1.048.576$)



Matrix-Vector Multiplication

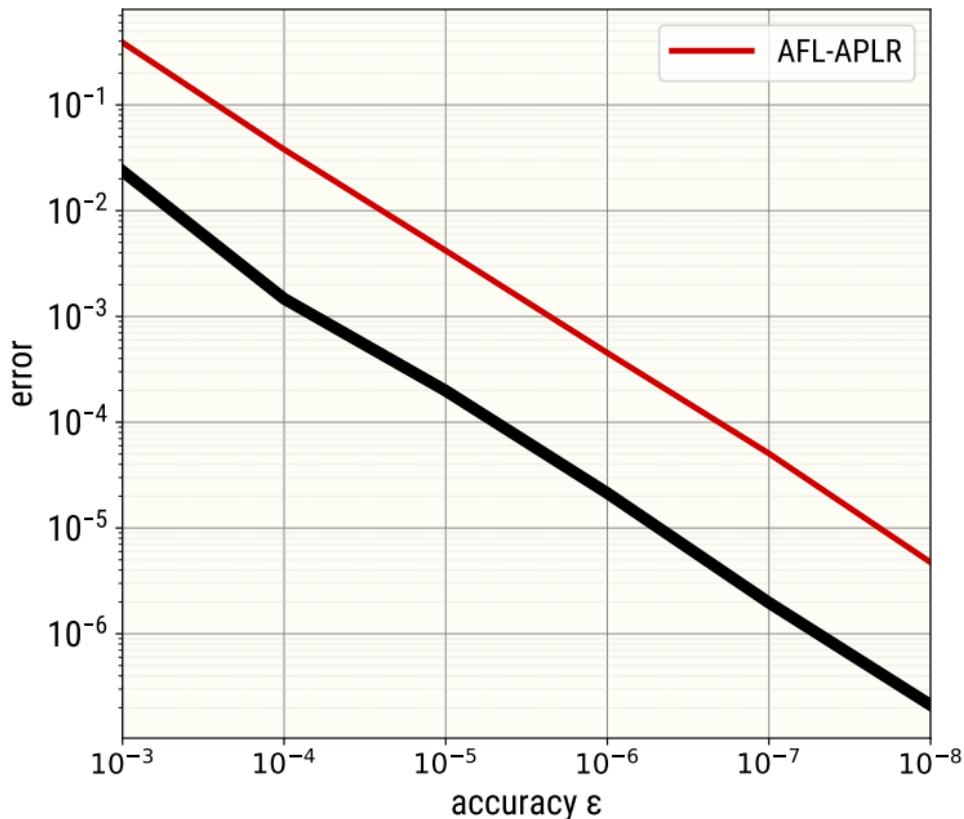
Laplace SLP ($n = 1.048.576$, AFL+APLR)

Matrix-Vector Multiplication

Laplace SLP ($n = 1.048.576$, AFLP+APLR, *on-the-fly*)

\mathcal{H} -LU Factorization

\mathcal{H} -LU Inversion Error $||I - M \cdot (LU)^{-1}||_2$



\mathcal{H} -LU Factorization

Problem

A significant error increase with standard \mathcal{H} -arithmetic.

Options

- ① tighter accuracy settings for compression during \mathcal{H} -arithmetic or
- ② use *accumulator based \mathcal{H} -arithmetic*¹ without compression of accumulator matrices.

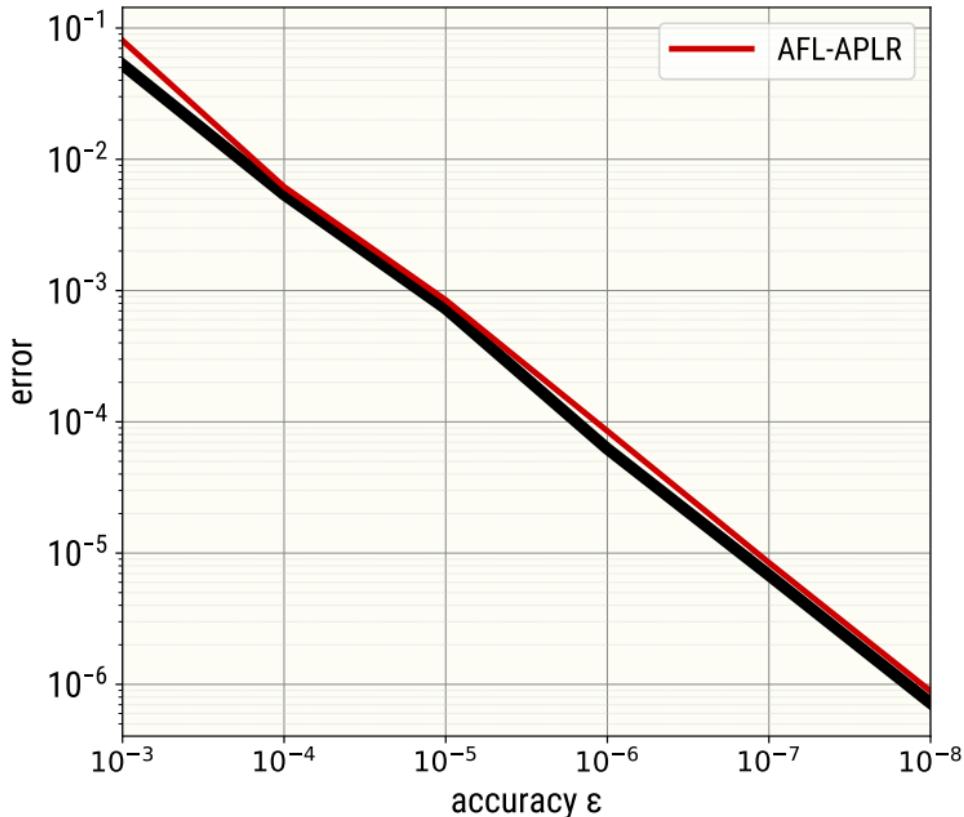
```

function HMUL( $C_{\tau,\sigma}, \mathcal{A}_{\tau,\sigma}, \mathcal{P}_{\tau,\sigma}$ )
  for all updates  $(A_{\tau,\rho}, B_{\rho,\sigma}) \in \mathcal{P}_{\tau,\sigma}$  do
    if  $A_{\tau,\rho}/B_{\rho,\sigma}$  are dense/lowrank then
       $\mathcal{A}_{\tau,\sigma} := \mathcal{A}_{\tau,\sigma} + A_{\tau,\rho}B_{\rho,\sigma};$ 
       $\mathcal{P}_{\tau,\sigma} := \mathcal{P}_{\tau,\sigma} \setminus \{(A_{\tau,\rho}, B_{\rho,\sigma})\};$ 
    if  $C_{\tau,\sigma}$  is structured then
      for all subblocks  $C_{\tau_i,\sigma_j}$  do
        hmul( $C_{\tau_i,\sigma_j}, \mathcal{A}_{\tau,\sigma}|_{\tau_i,\sigma_j}, \mathcal{P}_{\tau,\sigma}|_{\tau_i,\sigma_j}$ );
    else
       $C_{\tau,\sigma} := C_{\tau,\sigma} + \mathcal{A}_{\tau,\sigma};$            // Compression/Decompression
  
```

¹ Börm: "Hierarchical matrix arithmetic with accumulated updates", CVS 20, 71–84, 2019

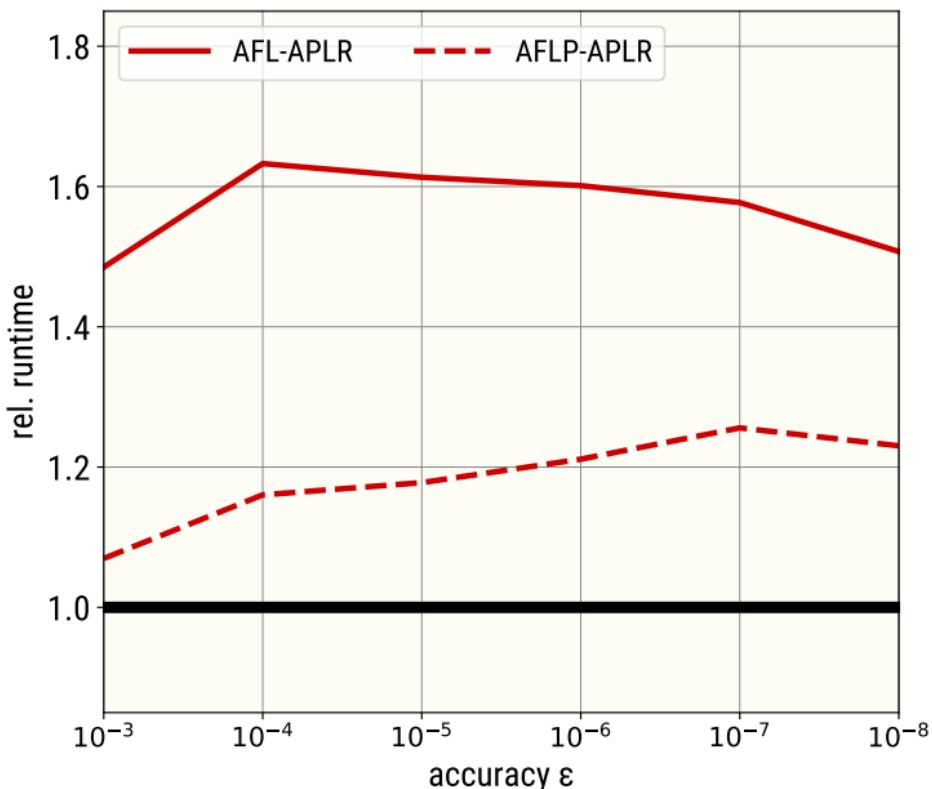
\mathcal{H} -LU Factorization

\mathcal{H} -LU Inversion Error $||I - A \cdot (LU)^{-1}||_2$ with Accumulator



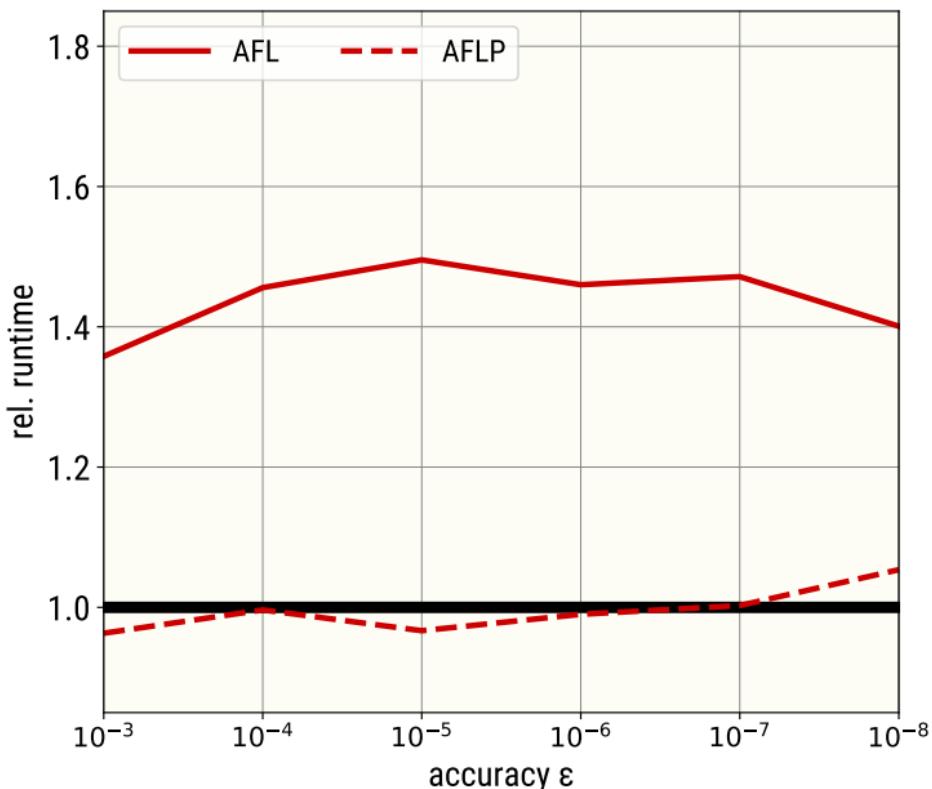
\mathcal{H} -LU Factorization

Laplace SLP ($n = 1.048.576$, AFL/AFLP, w/ APLR)



\mathcal{H} -LU Factorization

Laplace SLP ($n = 1.048.576$, AFL/AFLP, w/o APLR)



CONCLUSION

Conclusion

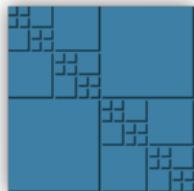
By using floating point compression storage for hierarchical lowrank matrices can be

- *significantly reduced*
- with *small impact* on (parallel) performance

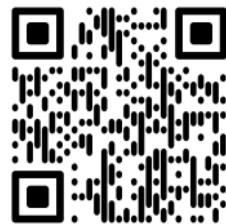
The memory gap between the \mathcal{H} -matrices, Uniform- \mathcal{H} -matrices and \mathcal{H}^2 -matrices can also be reduced by using *adaptive precision* compression for *lowrank* matrices.

Future Work

- adjustments to error control,
- more arithmetic with on-the-fly decompression



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