

Parallel \mathcal{H} -Matrices

Algorithms and Arithmetic

Ronald Kriemann

Winterschool on \mathcal{H} -Matrices

2024

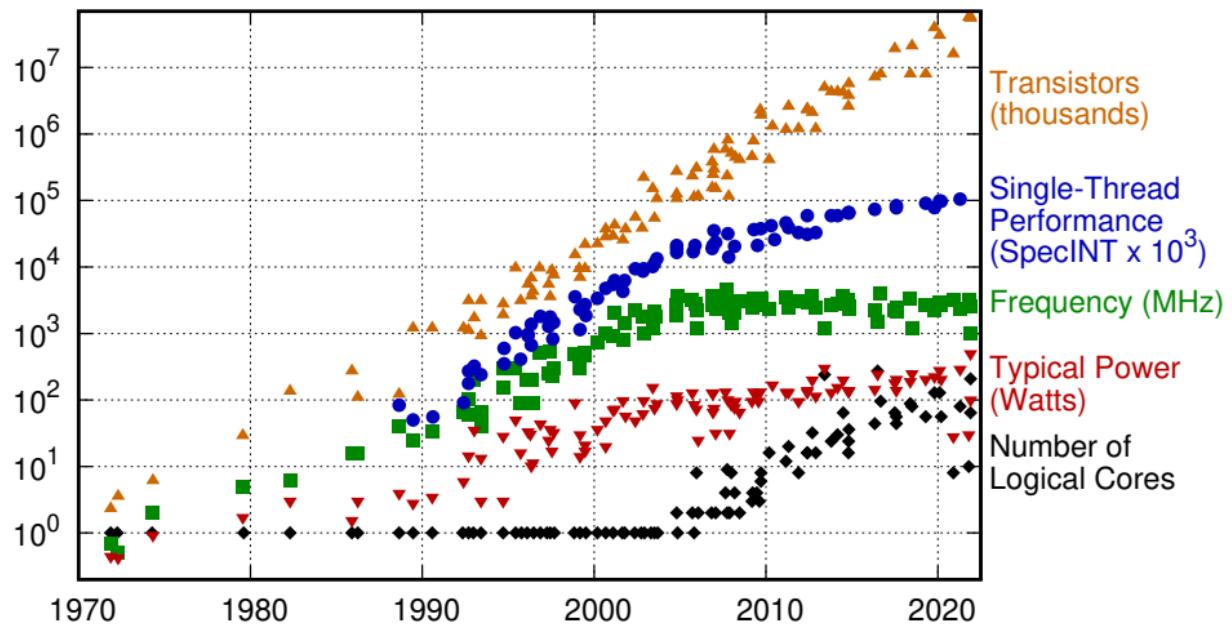
MAX PLANCK INSTITUTE
FOR MATHEMATICS IN THE SCIENCES



INTRODUCTION

The Free Lunch is over!¹

50 Years of Microprocessor Trend Data²

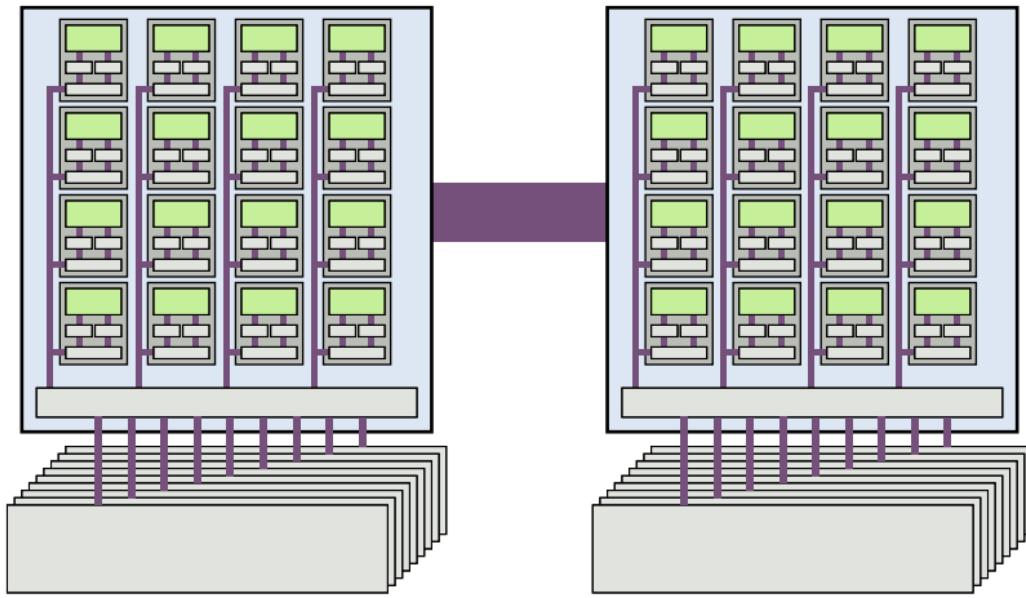


¹ H. Sutter: "The Free Lunch Is Over: A Fundamental Turn Toward Concurrency in Software", Dr. Dobb's Journal, 30(3), March 2005.

² K. Rupp: "Microprocessor Trend Data", <https://github.com/karlrupp/microprocessor-trend-data>

Parallel Systems

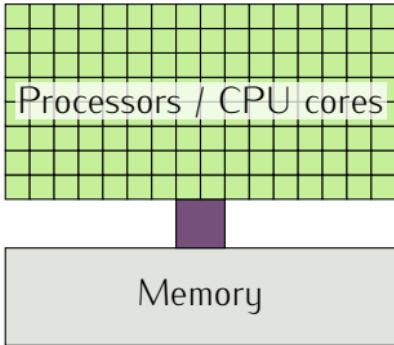
A typical compute server looks like this:



Each processor has several CPU cores and multiple levels of memory.

Parallel Systems

For programming, this is simplified to a *shared memory* system based on *symmetric multiprocessing*:

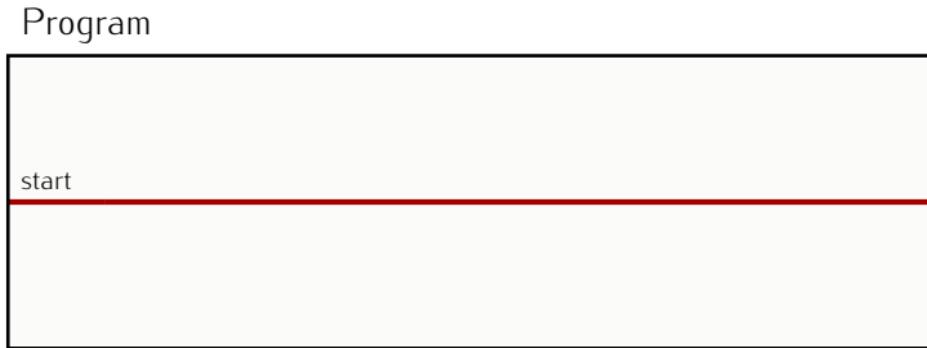


- All memory is *shared* by all processors.
- All processors/CPU cores are considered *equal*.

Threads

To enable shared memory parallelism, a program needs to use *threads*, i.e., parallel execution paths.

When a program starts, a single thread exists.

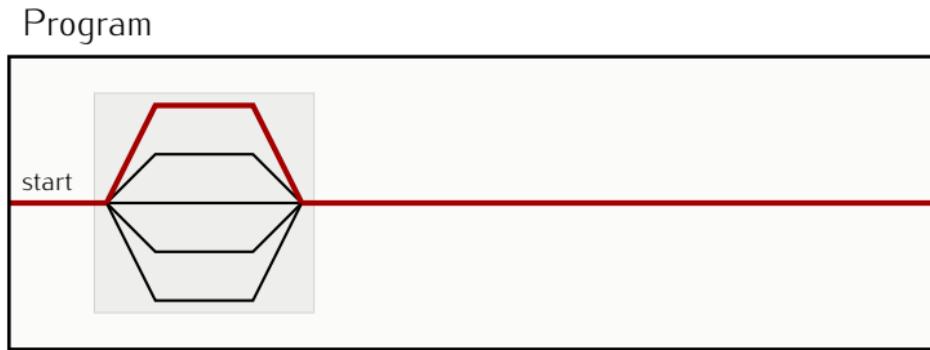


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One may then spawn new threads, which run in parallel with the existing, *master* thread.



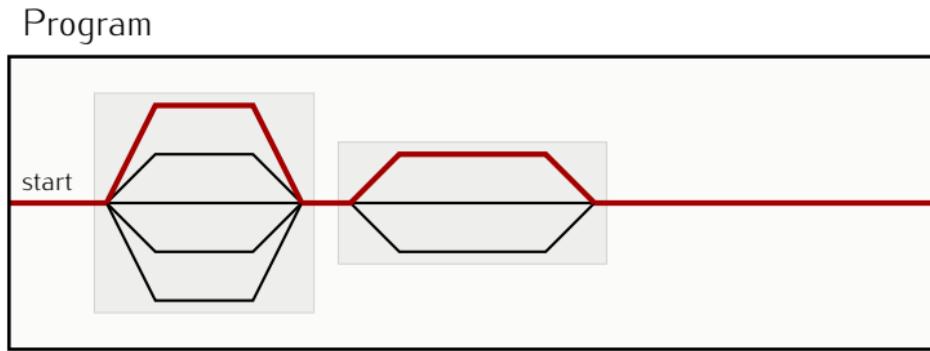
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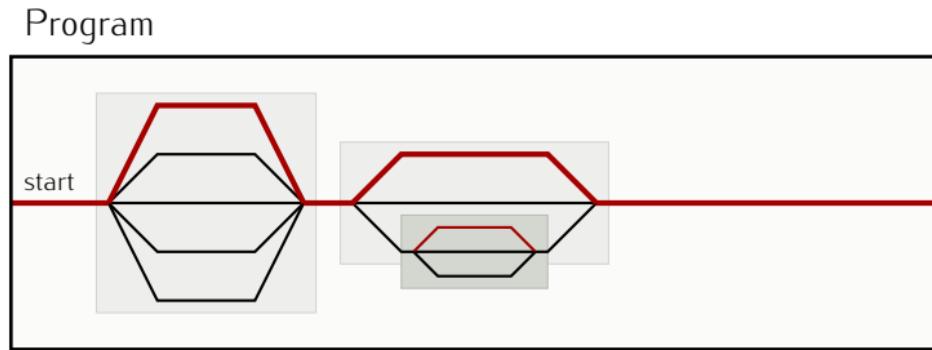
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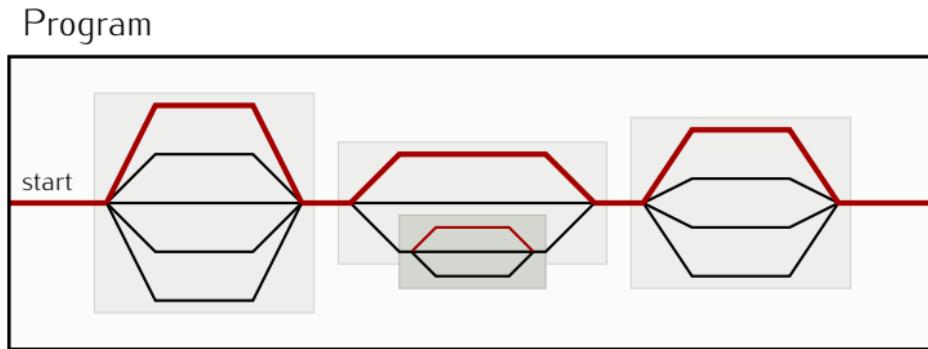
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Tasks and DAGs

Task

A task is considered an *atomic* computational unit, i.e. is not divided any further.

Different tasks of the same computation may be of different size.

The goal is to define as many *independent* tasks as possible to compute as much as possible in parallel.

Tasks and DAGs

Task

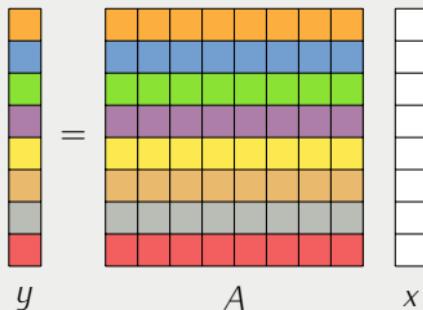
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Example: Dense Matrix-Vector Multiplication $y = Ax$

The computation may be split into tasks for each dot-product $y_i := \sum_j a_{ij}x_j$:



All of these n tasks are independent and may be computed in parallel.

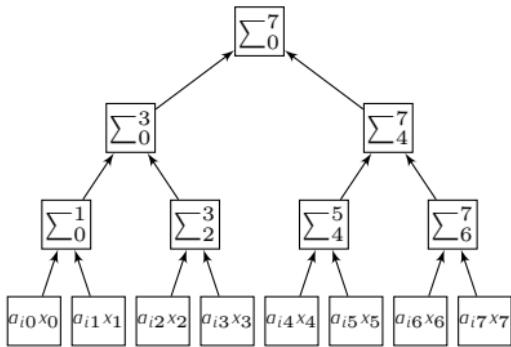
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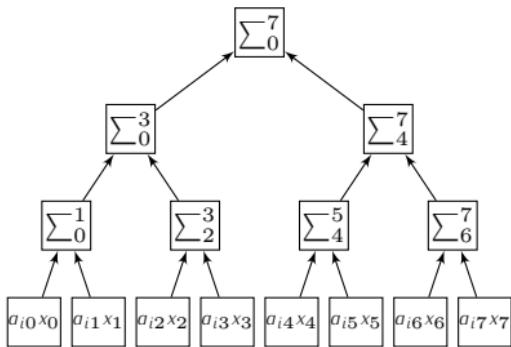


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Tasks and DAGs

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Some tasks of the computation now *depend* on the results of other tasks.

The dependencies form edges between tasks/nodes in a *directed acyclic graph* (DAG), the *task-dependency graph*.

Task Scheduling

Scheduling is the assignment of tasks to processors for the execution of the task.

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Example: \mathcal{H} -LU Factorization



Traditional Parallelization

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DAG-based Approach

Task Scheduling

Task scheduling is (normally) performed *automatically* by the *runtime system* enabling task based programming.

Available runtime systems:

- OpenMP
- StarPU
- PaRSEC
- TBB
- HPX
- C++-TaskFlow
- ...

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OPENMP

OpenMP started as a joined initiative of the major hardware and software vendors to provide compiler support for parallel programs.

1997: OpenMP 1.0 for Fortran

1998: OpenMP 1.0 for C/C++

2000: OpenMP 2.0 for Fortran with fixes and clarifications

2002: OpenMP 2.0 for C/C++

2005: OpenMP 2.5 combining Fortran and C/C++

2008: OpenMP 3.0 introduces *tasks*

2013: OpenMP 4.0 support for vector units and special targets

2015: OpenMP 4.5 taskloops

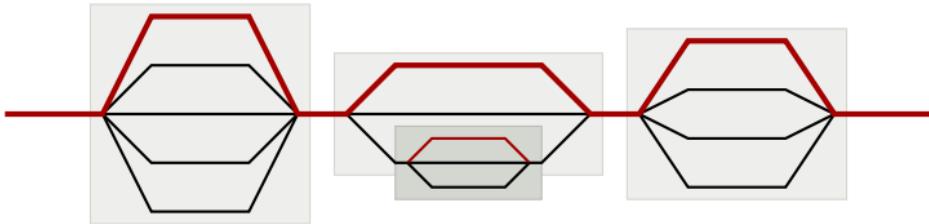
2018: OpenMP 5.0 taskloop reductions, C++ range loops

Beside the compiler directives (pragmas), OpenMP also contains a set of data types and functions, imported via the header file `omp.h`.

All major C/C++ and Fortran compilers support OpenMP.

The underlying model of OpenMP is the *fork-join model* which is based on threads:

A *master thread* creates a *team of worker threads* which run in parallel together with the master thread until all worker threads finish.



The number of threads in a team may differ in different parallel sections of the program.

OpenMP extends the underlying programming language by *compiler directives*.

Each OpenMP directive starts with the pragma

```
#pragma omp <directive> new-line
```

The directive is applied to the immediately following source code block, i.e.

```
void f () {  
    #pragma omp <directive>  
    {  
        ...  
    }  
  
    #pragma omp <directive>  
    ...  
}
```

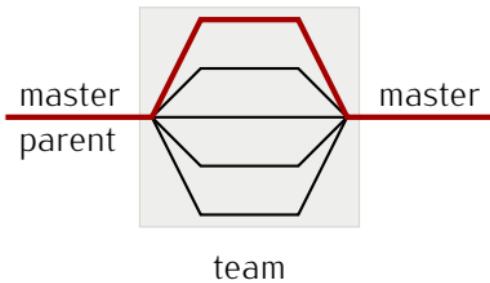
After the source code block, the worker threads of the thread team will stop and only the master thread will proceed.

A new team of threads is created by the directive

```
#pragma omp parallel
```

The thread encountering the `parallel` directive is called the *master* or *parent* thread of the created team.

```
void f () {  
    ...                                // executed by master thread  
    #pragma omp parallel  
    {  
        ...                            // executed by team  
    }  
    ...                                // executed by master thread  
}
```



Example: Hello World

```
#include <stdio.h>
int main () {
    printf( "Hello, world!\n" ); // executed by master thread
}
```

Example: Hello World

```
#include <stdio.h>
int main () {
    #pragma omp parallel
    printf( "Hello, world!\n" ); // executed by all threads
}
```

Example: Hello World

```
#include <stdio.h>
int main () {
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    printf( "Hello, world!\n" ); // executed by all threads
}
```

To enable OpenMP during compilation, a special compiler flag has to be provided:

```
> gcc -fopenmp -o hello -c hello.c
```

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```

Possible program outputs on a 4-Core CPU may be:

Hello, world!
Hello, world!
Hello, world!
Hello, world!

Hello, world!Hello, world!Hello, world!
Hello, world!

The garbled output is due to a *critical section* where all CPUs compete for the same output.

Remark

A typical programming mistake is to forget the parallel directive:

```
int main () {  
    #pragma omp           // no "parallel"  
    {  
        ...  
    }  
}
```

In this case, no new threads are created and the code will be executed by the master thread alone, i.e. **sequential** execution.

Loops

A standard loop in a program may be parallelized with the directive

```
#pragma omp for
```

Example: Vector addition $y := \alpha x + y$

```
void axpy ( int n, double alpha, double * x, double * y ) {  
  
    for ( int i = 0; i < n; ++i )  
        y[i] += alpha * x[i];  
}
```

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    for ( int i = 0; i < n; ++i )
        y[i] += alpha * x[i];
}
```

The parallel and the for directive may be joined:

```
void axpy ( int n, double alpha, double * x, double * y ) {
    #pragma omp parallel for
    for ( int i = 0; i < n; ++i )
        y[i] += alpha * x[i];
}
```

Shared and Private Data

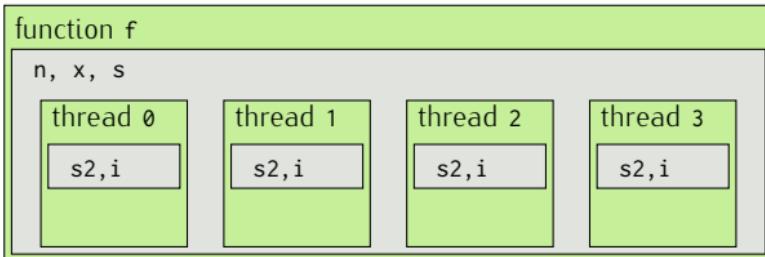
Data defined in the surrounding block of a parallel code block is *shared* by all threads. Data defined within a parallel code block is *private* to a specific thread.

At line 4, the variables `n`, `x` and `s` are already defined. In the block 5-13, these variables are then shared by all threads.

The variables `s2` and `i` are defined *within* the parallel code block and are therefore, private to each thread.

```

1 void f ( int n, double * x ) {
2     double s = 0.0;
3
4     #pragma omp parallel
5     {
6         double s2 = 0;
7
8         #pragma omp for
9         for ( int i = 0; i < n; ++i )
10            s2 += x[i];
11
12         s = s+s2;
13     }
14 }
```



Thread Dependencies

Any change to a shared variable will affect all threads of the thread team, and hence, defines a *critical section*.

```
1 void f ( int n, double * x ) {
2     double s = 0.0;
3
4 #pragma omp parallel
5 {
6     double s2 = 0;
7
8 #pragma omp for
9     for ( int i = 0; i < n; ++i ) // n : read-only
10        s2 += x[i];           // x : read-only
11
12
13    s = s+s2;             // s : read-write
14 }
15 }
```

At line 11 the shared variable `s` is updated, forming a critical section.

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5     {
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7
8         #pragma omp for
9         for ( int i = 0; i < n; ++i ) // n : read-only
10            s2 += x[i];           // x : read-only
11
12        #pragma omp critical
13        s = s+s2;             // s : read-write
14    }
15 }
```

At line 11 the shared variable `s` is updated, forming a critical section.

With the `critical` directive, a critical section is defined and ensured that only a single thread is in the section at any time. However, this then applies to *all* threads.

Thread Dependencies

A better approach are *mutexes*, which are standard variables and handled as such.

```
1 #include <omp.h>           // include OpenMP functions/types
2
3 void f ( int n, double * x ) {
4     double      s = 0.0;
5     omp_lock_t  mtx;          // define mutex variable
6
7     omp_init_lock( & mtx );    // initialize mutex
8
9 #pragma omp parallel           // mtx is a shared variable
10 {
11     double s2 = 0;
12
13     #pragma omp for
14     for ( int i = 0; i < n; ++i )
15         s2 += x[i];
16
17     omp_set_lock( & mtx );    // lock mutex
18     s = s+s2;
19     omp_unset_lock( & mtx );  // unlock mutex
20 }
21
22 omp_destroy_lock( & mtx );   // destroy mutex
23 }
```

Task based Computations

Since v3.0, OpenMP supports explicit task creation without thread binding:

```
#pragma omp task
```

Each task consists of

- *code* to execute and
- a *data environment*.

The code is defined by the code block:

```
#pragma omp task
{
    ...
        // code executed in task
}
```

All code reachable by code in the block defines the *task region*.

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Important:

- The construction time of a task and the execution time of a task may differ.
- The constructing thread of a task and the executing thread of a task may differ.

Task based Computations

All threads, which encounter a `task` directive, will generate a new task:

```
#pragma omp parallel
{
    for ( int i = 0; i < 4; ++i ) {
        #pragma omp task
        {
            ...
        } } }
```

Each of the p threads will execute the `parallel` code, generating $4 \cdot p$ tasks!

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        } } }
```

Each of the p threads will execute the `parallel` code, generating $4 \cdot p$ tasks!

If tasks should be generated only *once* for an algorithm, the `single` or `master` directive may be used:

```
#pragma omp parallel
{
    #pragma omp single
    for ( int i = 0; i < 4; ++i ) {
        #pragma omp task
        {
            ...
        } } }
```

Now, 4 tasks are generated but *all* team threads will execute the tasks.

Data Environment

The *data environment* of a task is the set of all variables which are in the scope of the task region.

shared

Shared variables will refer to the memory address at task construction. This address must be *valid* until the task has finished execution:

```
void f () {
    double x = produce_x();      // lifetime restricted to f, not the task
    #pragma omp task shared(x)
    { consume_x( x ); }         // error: x may no longer exist
}
```

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    { consume_x( x ); }         // error: x may no longer exist
}
```

firstprivate

Variable is defined with value at task construction. It is allocated and packaged together with the task code.

```
void f () {
    double x = produce_x();
    #pragma omp task firstprivate(x)
    { consume_x( x ); }         // ok: copy of x is packaged with task
}
```

Data Environment

private

Private variables will be uninitialized and hence, only allocated when the task is scheduled for execution.

By default, variables referenced in the task code block with no explicit data sharing rules are shared.

```
void f () {
    double x1 = 1.0;
    double x2 = 2.0;

    #pragma omp task firstprivate(x2)
    {
        double x3 = 4.0;    // private due to scope

        // x1 : shared      ( shared by all implicit tasks )
        // x2 : private     ( due to "firstprivate(x2)" )
        // x3 : private
    }
}
```

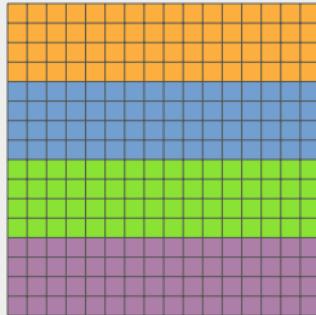
Task Loops

Loops can be automatically partitioned into tasks by the *taskloop* directive:

```
#pragma omp taskloop
```

Example: Matrix-Multiplication

```
void matmul ( int n, double * A, double * B, double * C ) {  
    #pragma omp parallel  
    #pragma omp single  
    #pragma omp taskloop  
    for ( int i = 0; i < n; ++i ) {  
        for ( int j = 0; j < n; ++j ) {  
            for ( int l = 0; l < n; ++l )  
                C[i+j*n] += A[i+l*n]*B[l+j*n];  
    } } }
```



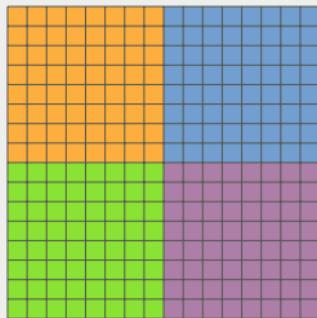
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```
void matmul ( int n, double * A, double * B, double * C ) {  
    #pragma omp parallel  
    #pragma omp single  
    #pragma omp taskloop collapse(2)  
    for ( int i = 0; i < n; ++i ) {  
        for ( int j = 0; j < n; ++j ) {  
            for ( int l = 0; l < n; ++l )  
                C[i+j*n] += A[i+l*n]*B[l+j*n];  
    } } }
```



With the *collapse(1)* option, loop decomposition is applied to l nested loops.

Task Dependencies

A task encountering a **task** directive becomes the *parent* task to the newly created *child* task.

Code in the code block of a child task is *not* part of the task region of the parent task:

```
#pragma omp task
{
    ...
        // part of parent task

    #pragma omp task
    {
        ...
            // part of child task, not of parent task
    }

    ...
        // part of parent task
}
```

After creating the child task, the parent may immediately proceed with the execution of it's task region.

Task Dependencies

Tasks may be part of a *task group*.

```
#pragma omp taskgroup
```

When finishing the task group, the parent tasks blocks and waits for all child tasks to finish.

```
double dot ( int n, double * x, double * y ) {
    double d1, d2;

    #pragma omp task
    d1 = dot( n/2, x, y );

    #pragma omp task
    d2 = dot( n/2, x + n/2, y + n/2 );

    return d1+d2;
}
```

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double dot ( int n, double * x, double * y ) {
    double d1, d2;

    #pragma omp taskgroup
    {
        #pragma omp task
        d1 = dot( n/2, x, y );

        #pragma omp task
        d2 = dot( n/2, x + n/2, y + n/2 );
    }                                         // wait for child tasks

    return d1+d2;
}
```

Task Dependencies

Full example for task based computation:

```
double dot ( int n, double * x, double * y ) {
    if ( n >= 32 ) {           // defines task granularity
        double d1, d2;         // parallel recursion

        #pragma omp taskgroup
        {
            #pragma omp task
            d1 = dot( n/2, x, y );
            #pragma omp task
            d2 = dot( n/2, x + n/2, y + n/2 );
        }                      // wait for child tasks/sub results
        return d1+d2;
    } else {
        double d = 0;           // sequential execution
        for ( int i = 0; i < n; ++i ) d += x[i] * y[i];
        return d;
    }
}

int main () {
    int n = ...; double * x = ...; double * y = ...;
    double d = 0;

    #pragma omp parallel    // start threads
    #pragma omp single      // ensure only single thread generates tasks
    #pragma omp task         // top-level task
    d = dot( n, x, y );
}
```

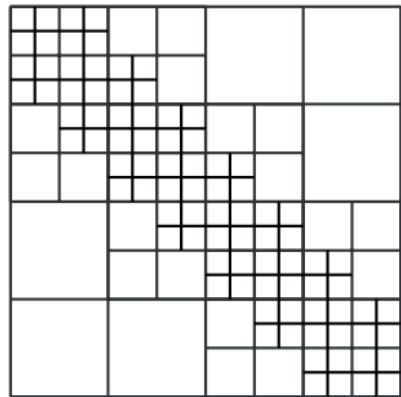
\mathcal{H} -MATRIX CONSTRUCTION

\mathcal{H} -Matrix Construction

Let I be an index set, $T(I)$ a \mathcal{H} -tree over I and $T = T(I \times I)$ a \mathcal{H}_x -tree over $T(I)$ with $\mathcal{L}(T)$ being the set of leaves of T .

The basic algorithm for \mathcal{H} -matrix construction is

```
function BUILD(( $\tau, \sigma$ ))
    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
        if  $(\tau, \sigma)$  is admissible then
            build low-rank matrix;
        else
            build dense matrix;
    else
        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
            build( $(\tau', \sigma')$ );
```

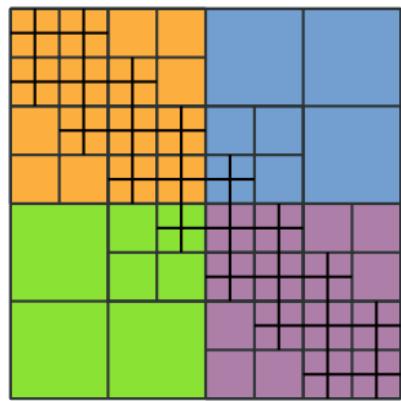


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```



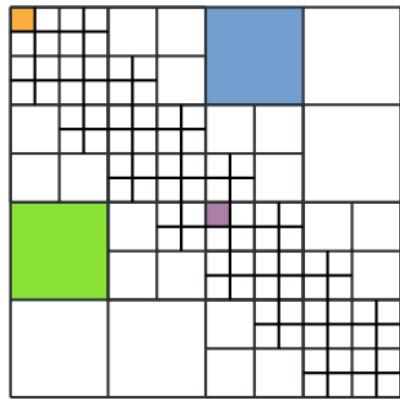
With classical OpenMP loop based parallelization would be used.

However, this may lead to the problems with load balancing.

\mathcal{H} -Matrix Construction

Using a task based approach, the algorithm looks as

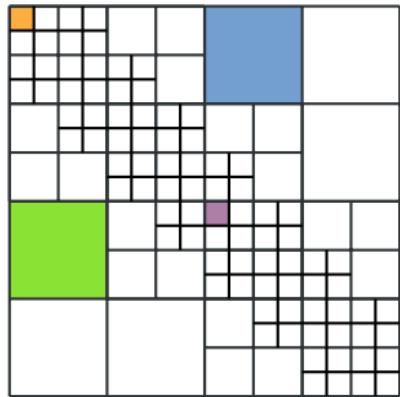
```
function BUILD(( $\tau, \sigma$ ))
    if ( $\tau, \sigma$ )  $\in \mathcal{L}(T)$  then
        #pragma omp task
        if ( $\tau, \sigma$ ) is admissible then
            build low-rank matrix;
        else
            build dense matrix;
    else
        for all ( $\tau', \sigma'$ )  $\in \mathcal{S}((\tau, \sigma))$  do
            build(( $\tau', \sigma'$ ));
```



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            build( $(\tau', \sigma')$ );
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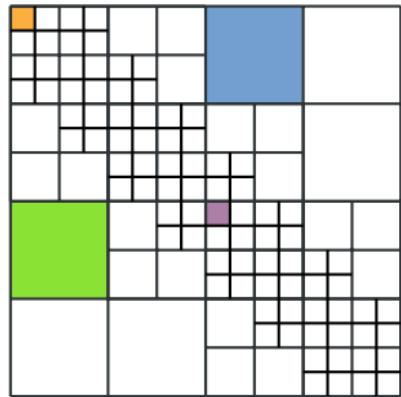


The construction of *each* node in T defines a new task.

\mathcal{H} -Matrix Construction

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            build low-rank matrix;
        else
            build dense matrix;
    else
        #pragma omp taskgroup      // optional
        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
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            build( $(\tau', \sigma')$ );
```

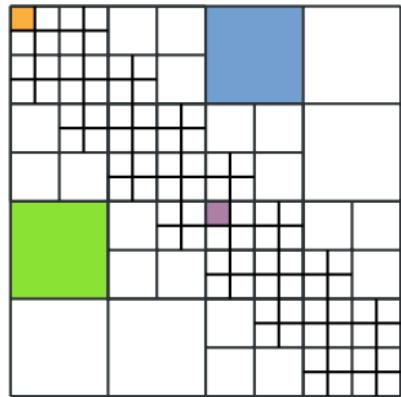


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```



The construction of *each* node in T defines a new task.

In \mathcal{H} -matrix construction:

- there are much more tasks than processors ($\#\mathcal{L}(T) \gg p$) and
- each leaf block can be built *independently*.

\mathcal{H} -Matrix Construction

hmatrix.c

```
phmatrix
build_from_block_hmatrix ( pcblock b, uint k ) {
    phmatrix h = NULL;

    if (b->son) {
        int rsons = b->rsons;
        int csons = b->csons;
        h = new_super_hmatrix( b->rc, b->cc, rsons, csons );

        for (int j = 0; j < csons; j++) {
            for (int i = 0; i < rsons; i++) {
                pcblock b1 = b->son[i+j*rsons];
                phmatrix h1 = build_from_block_hmatrix( b1, k );
                ref_hmatrix(h->son + i + j * rsons, h1);
            }
        }
    } else if (b->a > 0) {
        h = new_rk_hmatrix(b->rc, b->cc, k);
    } else {
        h = new_full_hmatrix(b->rc, b->cc);
    }

    update_hmatrix(h);
    return h;
}
```

example_hmatrix_bem3d.c

```
V = build_from_block_hmatrix(broot,m*m*m);
```

\mathcal{H} -Matrix Construction

hmatrix.c

```
phmatrix
build_from_block_hmatrix ( pcblock b, uint k ) {
    phmatrix h = NULL;

    if (b->son) {
        int rsons = b->rsons;
        int csons = b->csons;
        h = new_super_hmatrix( b->rc, b->cc, rsons, csons );

        #pragma omp taskgroup
        #pragma omp taskloop collapse(2)
        for (int j = 0; j < csons; j++) {
            for (int i = 0; i < rsons; i++) {
                pcblock b1 = b->son[i+j*rsons];
                phmatrix h1 = build_from_block_hmatrix( b1, k );
                ref_hmatrix(h->son + i + j * rsons, h1);
            }
        }
    } else if (b->a > 0) {
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    } else {
        h = new_full_hmatrix(b->rc, b->cc);
    }

    update_hmatrix(h);
    return h;
}
```

example_hmatrix_bem3d.c

```
#pragma omp parallel
#pragma omp single
#pragma omp task // optional
V = build_from_block_hmatrix(broot,m*m*m);
```

\mathcal{H} -Matrix Construction

block.c

```
void  
iterate_rowlist ( ... ) {  
    ...  
    #pragma omp taskgroup  
    #pragma omp taskloop  
    for (i = 0; i < rc->sons; i++)  
        iterate_rowlist( rc->son[i], rnames[i], pb1[i],  
                        (pardepth > 0 ? pardepth - 1 : 0),  
                        pre, post, data);  
    ...  
}
```

example_hmatrix_bem3d.c

```
#pragma omp parallel  
#pragma omp single  
assemble_bem3d_hmatrix(bem_slp, broot, V);
```

Numerical Results

Results for Laplace-SLP, $n = 131.072$

| Intel i7-13700 | | |
|----------------|---------|---------|
| # Cores | Runtime | Speedup |
| 1 | 67.0s | |

Numerical Results

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| 24 | 5.8s | 11.55x |

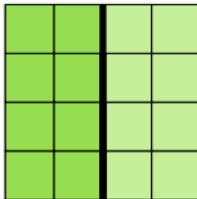
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Intel i7-13700

- 8 performance cores with max. 5.1 GHz,
- 8 efficiency cores with max. 4.1 GHz,



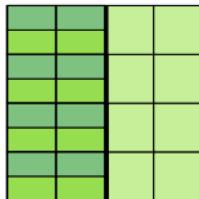
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| 8 | 8.4s | 7.98x |
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Intel i7-13700

- 8 performance cores with max. 5.1 GHz and two hyperthreads,
- 8 efficiency cores with max. 4.1 GHz,



\mathcal{H} -MATRIX-VECTOR MULTIPLICATION

\mathcal{H} -Matrix-Vector Multiplication

The standard \mathcal{H} -matrix-vector multiplication looks very similar to the construction algorithm:

```
function MATVEC( $M_{\tau,\sigma}, x, y$ )
    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
         $y|_\tau := y|_\tau + M_{\tau,\sigma}x|_\sigma$ 
    else
        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
            matvec( $M_{\tau',\sigma'}, x, y$ );
```

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        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
            #pragma omp task
            matvec( $M_{\tau',\sigma'}, x, y$ );
```

Again, each sub block multiplication can be defined as a new task.

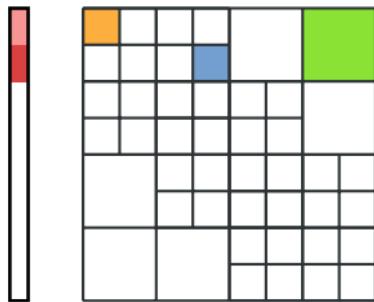
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function MATVEC( $M_{\tau,\sigma}, x, y$ )
    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
         $y|_\tau := y|_\tau + M_{\tau,\sigma}x|_\sigma$                                 // critical section
    else
        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
            #pragma omp task
            matvec( $M_{\tau',\sigma'}, x, y$ );
```

Again, each sub block multiplication can be defined as a new task.

However, the update of y_τ forms a critical section as more than one task may update the same vector.



\mathcal{H} -Matrix-Vector Multiplication

Solution 1

Add a mutex to guard the critical section.

| Intel i7-13700 | |
|----------------|---------|
| Runtime | Speedup |
| sequential: | 9.12s |

```
function MATVEC( $M_{\tau,\sigma}, x, y, \text{ mtx}$ )
    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
        omp_set_lock( mtx );
         $y|_\tau := y|_\tau + M_{\tau,\sigma}x|_\sigma;$ 
        omp_unset_lock( mtx );
    else
        for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
            #pragma omp task
            matvec( $M_{\tau',\sigma'}, x, y, \text{ mtx}$ );
```

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| Intel i7-13700 | | |
|----------------|---------|---------|
| | Runtime | Speedup |
| sequential: | 9.12s | |
| parallel: | 59.60s | 0.15x |

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    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
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        omp_unset_lock( mtx );
    else
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```

Solution 2

Split local computation and update of y .

| i7-13700 | |
|-------------|-------|
| | |
| sequential: | 9.12s |
| parallel: | |

```

function MATVEC( $M_{\tau,\sigma}, x, y, \text{mtx}$ )
  if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
     $t := M_{\tau,\sigma}x|_\sigma;$  // local matvec
    omp_set_lock( mtx );
     $y|_\tau := y|_\tau + t;$  // update
    omp_unset_lock( mtx );
  else
    for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
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    for all  $(\tau', \sigma') \in \mathcal{S}((\tau, \sigma))$  do
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Solution 2

Split local computation and update of y .

| i7-13700 | |
|-------------|--------------|
| | |
| sequential: | 9.12s |
| parallel: | 3.41s / 2.7x |

```

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```

Solution 2

Split local computation and update of y .

| | i7-13700 | 2x Epyc 9554 |
|-------------|--------------|--------------|
| sequential: | 9.12s | 14.89s |
| parallel: | 3.41s / 2.7x | 5.90s / 2.5x |

```

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```

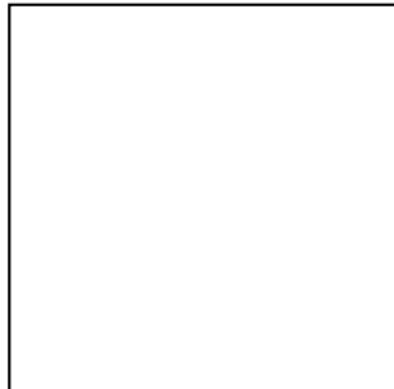
\mathcal{H} -Matrix-Vector Multiplication

Solution 3

Lock-free approach by block-row oriented recursion.

| | i7-13700 | 2x Epyc 9554 |
|-------------|----------|--------------|
| sequential: | 9.12s | 14.89s |
| parallel: | | |

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    else
        #pragma omp taskgroup
        for all  $\tau' \in \mathcal{S}(\tau)$  do
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            for all  $\sigma' \in \mathcal{S}(\sigma)$  do
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```



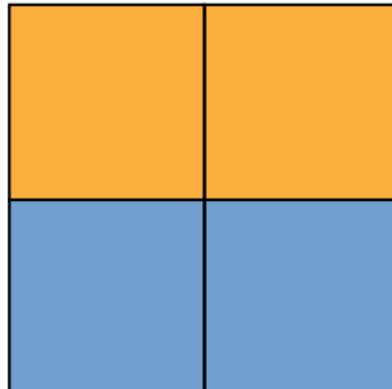
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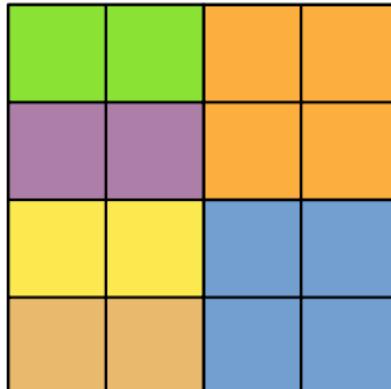
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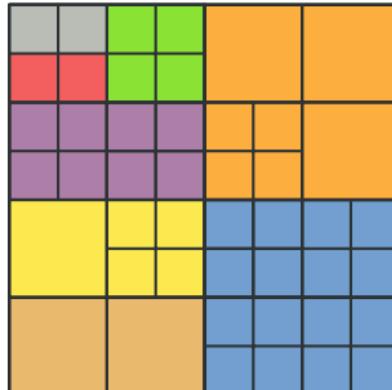
\mathcal{H} -Matrix-Vector Multiplication

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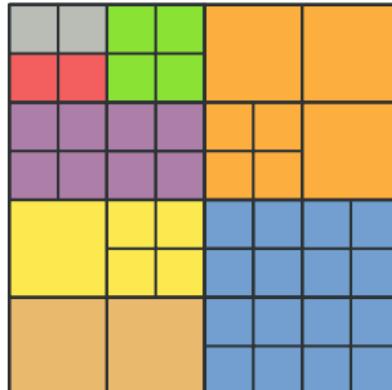
\mathcal{H} -Matrix-Vector Multiplication

Solution 3

Lock-free approach by block-row oriented recursion.

| | i7-13700 | 2x Epyc 9554 |
|-------------|--------------|---------------|
| sequential: | 9.12s | 14.89s |
| parallel: | 3.62s / 2.5x | 0.98s / 15.2x |

```
function MATVEC( $M_{\tau,\sigma}, x, y$ )
    if  $(\tau, \sigma) \in \mathcal{L}(T)$  then
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\mathcal{H} -Matrix-Vector Multiplication

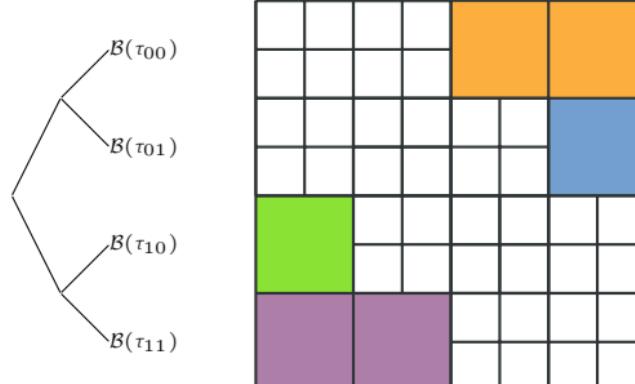
Solution 3 (optimised)

Keep list of matrix blocks per row cluster
and handle all such blocks in single task..

i7-13700 2x Epyc 9554

| | | |
|-------------|-------|--------|
| sequential: | 9.12s | 14.89s |
| parallel: | | |

```
function MATVEC( $\tau, \mathcal{B}, x, y$ )
    if  $\mathcal{B}(\tau) \neq \emptyset$  then
        for all  $M' \in \mathcal{B}(\tau)$  do
             $y|_{\tau} := y|_{\tau} + M'_{\tau, \sigma} x|_{\sigma};$ 
    else
        #pragma omp taskgroup
        for all  $\tau' \in \mathcal{S}(\tau)$  do
            #pragma omp task
            matvec( $\tau', \mathcal{B}, x, y$ );
```



\mathcal{H} -Matrix-Vector Multiplication

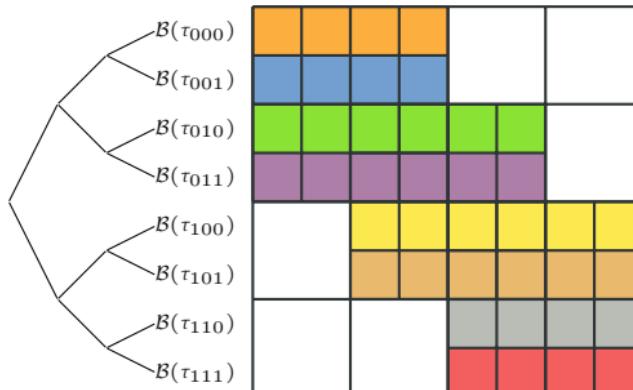
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i7-13700 2x Epyc 9554

| | | |
|-------------|-------|--------|
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```



\mathcal{H} -Matrix-Vector Multiplication

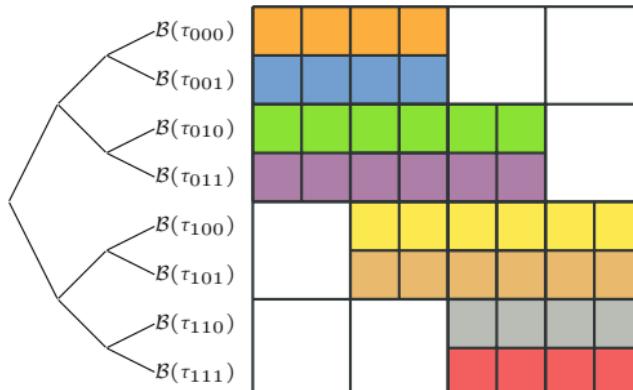
Solution 3 (optimised)

Keep list of matrix blocks per row cluster
and handle all such blocks in single task..

i7-13700 2x Epyc 9554

| | | |
|-------------|--------------|---------------|
| sequential: | 9.12s | 14.89s |
| parallel: | 3.45s / 2.6x | 0.56s / 26.6x |

```
function MATVEC( $\tau, \mathcal{B}, x, y$ )
    if  $\mathcal{B}(\tau) \neq \emptyset$  then
        for all  $M' \in \mathcal{B}(\tau)$  do
             $y|_{\tau} := y|_{\tau} + M'_{\tau, \sigma} x|_{\sigma};$ 
    else
        #pragma omp taskgroup
        for all  $\tau' \in \mathcal{S}(\tau)$  do
            #pragma omp task
            matvec( $\tau', \mathcal{B}, x, y$ );
```



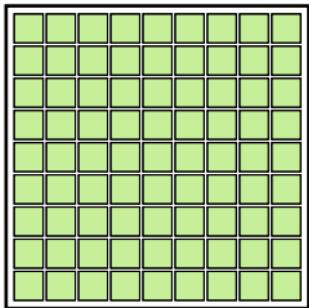
\mathcal{H} -Matrix-Vector Multiplication

Solution 3 (optimised)

Keep list of
an handle a

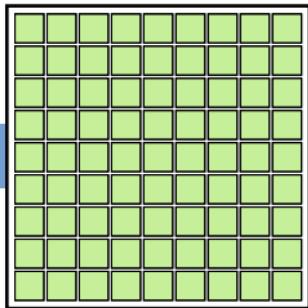
sequential:
parallel:

Epyc 9554



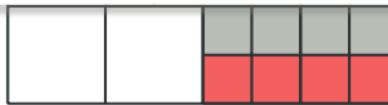
function MATVEC($\tau, \mathcal{B} \times u$)

Epyc 9554



```
do  
   $\sigma X | \sigma$ ;  
  
group  
  ) do  
    task  
    ,  $\mathcal{B}, x, y$ ;
```

$\mathcal{B}(\tau_{110})$
 $\mathcal{B}(\tau_{111})$



\mathcal{H} -Matrix-Vector Multiplication

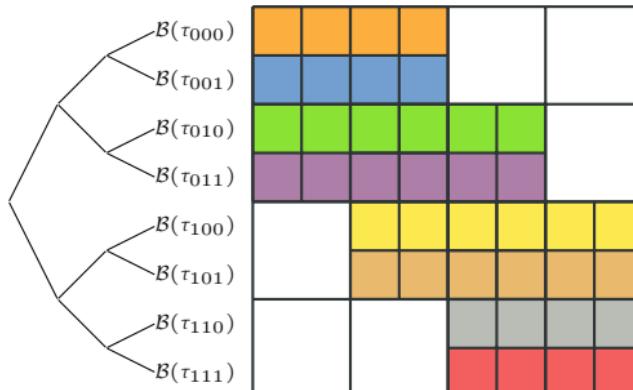
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    else
        #pragma omp taskgroup
        for all  $\tau' \in \mathcal{S}(\tau)$  do
            #pragma omp task
            matvec( $\tau', \mathcal{B}, x, y$ );
```



Implementation

Sequential multiplication in `hmatrix.c`:

```
void fastaddeval_hmatrix_avector ( field alpha, pchmatrix hm, pcavector x, pavector y )
{
    if      (hm->r) { addeval_rkmatrix_avector(alpha, hm->r, x, y); }
    else if (hm->f) { mvm_amatrix_avector(alpha, false, hm->f, x, y); }
    else {
        uint rsons = hm->rsons;
        uint csons = hm->csons;
        uint xoff  = 0;

        for ( uint j = 0; j < csons; j++ ) {
            avector xtmp;
            pavector x1  = init_sub_avector(&xtmp, (pavector) x, hm->son[j * rsons]->cc->size, xoff);
            uint     yoff = 0;

            for (uint i = 0; i < rsons; i++) {
                avector ytmp;
                pavector y1   = init_sub_avector(&ytmp, y, hm->son[i]->rc->size, yoff);

                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1);
                uninit_avector(y1);
                yoff += hm->son[i]->rc->size;
            }

            uninit_avector(x1);
            xoff += hm->son[j * rsons]->cc->size;
        }
    }
}
```

Implementation

Guard leaf block multiplication by mutex:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{
    if ( hm->r || hm->f ) {
        omp_set_lock( mtx );
        if ( hm->r ) addeval_rkmatrix_avector(alpha, hm->r, x, y);
        else           mvm_amatrix_avector(alpha, false, hm->f, x, y);
        omp_unset_lock( mtx );
    } else {
        ...
        for ( uint j = 0; j < csons; j++ ) {
            ...
            for ( uint i = 0; i < rsons; i++ ) {
                ...
                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
                ...
            } } } }
```

Implementation

Split computation and application of local update:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{
    if ( hm->r || hm->f ) {
        pavector t = new_avector( y->dim );
        clear_avector( t );
        if ( hm->r ) addeval_rkmatrix_avector(alpha, hm->r, x, t);
        else           mvm_amatrix_avector(alpha, false, hm->f, x, t);

        omp_set_lock( mtx );
        add_avector( 1.0, t, y );
        omp_unset_lock( mtx );
        del_avector( t );
    } else {
        ...
        for ( uint j = 0; j < csons; j++ ) {
            ...
            for ( uint i = 0; i < rsons; i++ ) {
                ...
                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
            }
        }
    }
}
```

Implementation

Define tasks:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{
    ...
} else {
    uint rsons = hm->rsons;
    uint csons = hm->csons;
    uint xoff  = 0;

    for ( uint j = 0; j < csons; j++ ) {
        avector xtmp;
        pavector x1 = init_sub_avector(&xtmp, (pavector) x, hm->son[j * rsons]->cc->size, xoff);
        uint yoff = 0;

        for ( uint i = 0; i < rsons; i++ ) {
            #pragma omp task
            {
                avector ytmp;
                pavector y1 = init_sub_avector(&ytmp, y, hm->son[i]->rc->size, yoff);

                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
                uninit_avector(y1);
                yoff += hm->son[i]->rc->size;
            }
            uninit_avector(x1);
            xoff += hm->son[j * rsons]->cc->size;
        }
    }
}
```

Implementation

Define tasks:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{
    ...
} else {
    uint rsons = hm->rsons;
    uint csons = hm->csons;
    uint xoff  = 0;

    for ( uint j = 0; j < csons; j++ ) {
        avector xtmp;
        pavector x1 = init_sub_avector(&xtmp, (pavector) x, hm->son[j * rsons]->cc->size, xoff);
        uint yoff = 0;

        for ( uint i = 0; i < rsons; i++ ) {
            #pragma omp task shared(alpha,y,mtx,rsons,csons,xoff,xtmp,x1,yoff,j,i)
            {
                avector ytmp;
                pavector y1 = init_sub_avector(&yttmp, y, hm->son[i]->rc->size, yoff);

                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
                uninit_avector(y1);
                yoff += hm->son[i]->rc->size;
            }
            uninit_avector(x1);
            xoff += hm->son[j * rsons]->cc->size;
        }
    }
}
```

Implementation

Define tasks:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{ ...
} else {
    uint rsons = hm->rsons;
    uint csons = hm->csons;
    uint xoff  = 0;

    for ( uint j = 0; j < csons; j++ ) {
        avector xtmp;
        pavector x1 = init_sub_avector(&xtmp, (pavector) x, hm->son[j * rsons]->cc->size, xoff);
        uint yoff = 0;

        for ( uint i = 0; i < rsons; i++ ) {
            #pragma omp task firstprivate(j,i,xoff,yoff,rsons,csons,alpha,y)
            {
                avector ytmp;
                pavector y1 = init_sub_avector(&yttmp, y, hm->son[i]->rc->size, yoff);

                fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
                uninit_avector(y1);

            }
            yoff += hm->son[i]->rc->size;
        }
        uninit_avector(x1);
        xoff += hm->son[j * rsons]->cc->size;
    } } }
```

Implementation

Define tasks:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{ ...
} else {
    uint rsons = hm->rsons;
    uint csons = hm->csons;
    uint xoff  = 0;

#pragma omp taskgroup
for ( uint j = 0; j < csons; j++ ) {
    avector xtmp;
    pavector x1  = init_sub_avector(&xtmp, (pavector) x, hm->son[j * rsons]->cc->size, xoff);
    uint     yoff = 0;

    for (uint i = 0; i < rsons; i++) {
        #pragma omp task firstprivate(j,i,xoff,yoff)
        {
            avector ytmp;
            pavector y1 = init_sub_avector(&yttmp, y, hm->son[i]->rc->size, yoff);

            fastaddeval_hmatrix_avector(alpha, hm->son[i + j * rsons], x1, y1, mtx);
            uninit_avector(y1);

        }
        yoff += hm->son[i]->rc->size;
    }
    uninit_avector(x1);
    xoff += hm->son[j * rsons]->cc->size;
} } }
```

Implementation

Task private data:

```
void fastaddeval_hmatrix_avector_omp ( field alpha, ..., pavector y, omp_lock_t * mtx )
{
    ...
} else {
    uint    rsons = hm->rsons;
    uint    csons = hm->csons;
    uint * rofs = allocuint( rsons );
    uint * cofs = allocuint( csons );

    for ( uint j = 0; j < csons; j++ ) { cofs[j] = xofs; xofs += hm->son[j * rsons]->cc->size; }
    for ( uint i = 0; i < rsons; i++ ) { rofs[i] = yofs; yofs += hm->son[i]->rc->size; }

#pragma omp taskgroup
{
    #pragma omp taskloop collapse(2)
    for ( uint j = 0; j < csons; j++ ) {
        for ( uint i = 0; i < rsons; i++ ) {
            avector  xtmp, ytmp;
            pavector x1 = init_sub_avector( &xtmp, (pavector) x, hm->son[j * rsons]->cc->size, cofs[j] );
            pavector y1 = init_sub_avector( &ytmp, y, hm->son[i]->rc->size, rofs[i] );

            fastaddeval_hmatrix_avector_omp( alpha, hm->son[i + j * rsons], x1, y1, mtx );

            uninit_avector( y1 );
            uninit_avector( x1 );
        } } } }
```

\mathcal{H} -MATRIX MULTIPLICATION

\mathcal{H} -Matrix Multiplication

We consider the general update

$$C := C + \alpha A \cdot B$$

A full parallel approach with tasks for *each* sub-block multiplication looks as

```
function MUL( $\alpha, A_{\tau,\rho}, B_{\rho,\sigma}, C_{\tau,\sigma}$ )
  if  $A_{\tau,\rho}, B_{\rho,\sigma}, C_{\tau,\sigma}$  are block matrices then
    #pragma omp taskloop collapse(3) firstprivate( $\alpha, A_{\tau,\rho}, B_{\rho,\sigma}, C_{\tau,\sigma}$ )
    for  $\tau' \in \mathcal{S}(\tau)$  do
      for  $\sigma' \in \mathcal{S}(\sigma)$  do
        for  $\rho' \in \mathcal{S}(\rho)$  do
          mul(  $\alpha, A_{\tau',\rho'}, B_{\rho',\sigma'}, C_{\tau',\sigma'}$  );
    else
       $C_{\tau,\sigma} := C_{\tau,\sigma} + \alpha A_{\tau,\rho} B_{\rho,\sigma};$  // critical section
```

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  if  $A_{\tau,\rho}, B_{\rho,\sigma}, C_{\tau,\sigma}$  are block matrices then
    #pragma omp taskloop collapse(3) firstprivate( $\alpha, A_{\tau,\rho}, B_{\rho,\sigma}, C_{\tau,\sigma}$ )
    for  $\tau' \in \mathcal{S}(\tau)$  do
      for  $\sigma' \in \mathcal{S}(\sigma)$  do
        for  $\rho' \in \mathcal{S}(\rho)$  do
          mul(  $\alpha, A_{\tau',\rho'}, B_{\rho',\sigma'}, C_{\tau',\sigma'}$  );
    else
      omp_set_lock(mutex( $C_{\tau,\sigma}$ ));
       $C_{\tau,\sigma} := C_{\tau,\sigma} + \alpha A_{\tau,\rho} B_{\rho,\sigma};$  // critical section
      omp_unset_lock(mutex( $C_{\tau,\sigma}$ ));
```

Each matrix block has an associated mutex.

\mathcal{H} -Matrix Multiplication

C++ implementation with OpenMP:

```
void multiply_task( alpha, op_A, A, op_B, B, C, acc, approx ) {
    if ( is_blocked_all( A, B, C ) ) {
        auto BA, BB, BC = ... ;

        #pragma omp taskloop collapse(3) firstprivate(alpha,op_A,op_B)
        for ( uint i = 0; i < BC->nblock_rows(); ++i ) {
            for ( uint j = 0; j < BC->nblock_cols(); ++j ) {
                for ( uint l = 0; l < BA->nblock_cols( op_A ); ++l ) {
                    auto C_ij = BC->block(i,j);
                    auto A_il = BA->block( i, l, op_A );
                    auto B_lj = BB->block( l, j, op_B );

                    multiply_task< value_t >( alpha, op_A, *A_il, op_B, *B_lj, *C_ij, acc, approx );
                } } } }
    else
        multiply( alpha, op_A, A, op_B, B, C, acc, approx );
}

void multiply( ..., lrmatrix< value_t > & A, lrmatrix< value_t > & B, dense_matrix< value_t > & C ) {
    auto T = blas::prod( value_t(1), blas::adjoint( A.V( op_A ) ), B.U( op_B ) );
    auto UT = blas::prod( value_t(1), A.U( op_A ), T );

    std::scoped_lock lock( C.mutex() );
    auto DC = C.mat();

    blas::prod( alpha, UT, blas::adjoint( B.V( op_B ) ), value_t(1), C.mat() );
}
```

\mathcal{H} -Matrix Multiplication

Results for Laplace-SLP, $n = 131.072$

| Intel i7-13700 | | |
|----------------|---------|---------|
| # Cores | Runtime | Speedup |
| 1 | 145.9s | |
| 2 | 76.8s | 1.90x |
| 4 | 38.7s | 3.77x |
| 8 | 21.6s | 6.75x |
| 16 | 19.4s | 7.52x |
| 24 | 17.4s | 8.38x |

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| AMD Epyc 9554 | | |
|---------------|---------|---------|
| # Cores | Runtime | Speedup |
| 1 | 202.80s | |
| 64 | 3.54s | 57.29x |
| 128 | 1.88s | 107.87x |

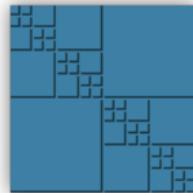
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